Regression Testing with GZoltar: Techniques for Test Suite Minimization, Selection, and Prioritization

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Mestrado Integrado em Engenharia Informática e Computação

Supervisor: Rui Abreu (PhD)

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Abstract

Software testing occurs simultaneously during the software development to detect errors as early as possible and to guarantee that changes made in software did not affect the system negatively.

However, during the development phase, the test suite is updated and tends to increase in size. Due to the resource and time constraints for re-executing large test suites, it is important to develop techniques to reduce the effort of regression testing. Several approaches have been studied to reduce the effort of regression testing: test suite minimization, selection, and prioritization. Test suite minimization techniques aims at identifying and eliminating redundant test cases from the suite. Test suite selection techniques identifies a subset of test cases from suite, required to re-test the changes in the software. Test suite prioritization techniques schedule test cases for execution in an order to increase the early fault detection.

Although, the approaches present the literature have some limitations (resources, times, etc.). In this manuscript we propose a new approach to the minimization, selection and prioritization problem that try to overcomes these limitation.

Our approach allows for (1) easy encoding of the relation between a test case and a component (source code statement) in a coverage matrix, (2) mapping this matrix in a set of constraints, and (3) computing optimal solutions (with the same coverage and fault detection of original set of tests) to minimization and selection problems by leveraging a fast and scalable constraint solver.

We implemented our approach in a Eclipse plug-in called GZOLTAR, which is perfectly integrated in the IDE and provides functions to debugging a software program using visualization in OpenGL. Features for regression tests were implemented with the name Regression-Zoltar, RZOLTAR for short.

To test our toolset, we conducted experiments to measure the efficiency and the size of regression suite. In particular, we evaluated our tool using real-world and large programs, as well as a user study in order to measure its usability. In our empirical evaluation, we show how RZOLTAR can be used to instantiate large-programs and efficiently find an solution for such problems. Our experiments show that our approach can significantly reduce the size of original test suite, and a corresponding reduction in the cost of regression testing. We also make a user study to find if we are in right way in terms of usability and functionalities.
Acknowledgements

This thesis would have not been possible without the help of some several people.

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Porto, February 14, 2012

Zé Carlos
“Code without tests is broken as designed”

Jacob Kaplan-Moss
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Abbreviations

APFD  Average Percent of Fault-Detection
API  Application Programming Interface
ARC  Ames Research Center
ASEJ  Automated Software Engineering Journal
BN  Bayesian Networks
CDG  Control Dependence Graph
CFG  Control Flow Graph
CPT  Conditional Probability Distribution Table
CPU  Central Processing Unit
CSP  Constraint Satisfaction Problem
CVS  Concurrent Versions System
DA  Diagnosis Algorithm
FCA  Formal Concept Analysis
FEUP  Faculty of Engineering - University of Porto
IDE  Integrated Development Environment
IJCICG  International Journal of Creative Interfaces and Computer Graphics
IJUP  Investigação Jovem na Universidade do Porto
IL  Integer Programming
ILP  Integer Linear Programming
ISSTA  International Symposium on Software Testing and Analysis
LOC  Lines of Code
LRU  Last Recently Used
MS  Mutation Score
MSC  Minimum Set Cover
ABBREVIATIONS

**OpenGL** Open Graphics Library

**PARC** Palo Alto Research Center

**RTS** Regression Testing Selection

**SIR** Software Infrastructure Repository

**SUT** Software Under Test

**TSL** Test Specification Language

**VM** Virtual Machine
Chapter 1

Introduction

During the software development cycle, the phase of tests is in general the most important method to determine whether the software diverge from the requirements or not. There, testing is a principal part of the development and maintenance phases of any software system, from the very small to the huge. Therefore, probably, the intension of testing increases exponentially with the product size and its desired level of reliability required [LH88].

![V-model of the Systems Engineering Process](image)

Figure 1.1: V-model of the Systems Engineering Process [Som07].

Normally, software testing is executed in different phases and there is a short relationship with the several phase of the cycle of software development. As we can see in Figure 1.1, at the time of module development, *unit testing* is accomplished. When main software components are combined to produce several of the subsystems, *integration testing* occurs. When all system exists as a complete entity, happens the *system testing* phase. Finally, *acceptance testing* is the phase of testing used to verify if the system cover all requirement which specified in the requirements analysis phase. In theory, all test phases must complement each other and share the same goal,
which is, try to hide faults that appears in specification, and/or implementation of the software [VF98].

1.1 Regression Testing

Software that has been changed (to fix some known fault or to delete/add new requirement) must be validated (retested) with focus in the following objectives: (1) assure that the new requirements have been implemented correctly; (2) ensure that new requirements do not affect previous functionalities (which continue working as expected); (3) test those parts of the software that have not been checked before. The process of retesting the software to ensure that modified program still work correctly with all of the test cases used to test original program (objective 2) is known as regression testing [VF98].

In recent years, the software testing research community have given enough importance to the subject of regression testing. Some approaches have been presented to maximize the test suite of each SUT: minimization, selection and prioritization. Test suite minimization is the technique to denote what test cases are redundant or obsolete and then remove them from the test suite. Test suite selection choose a subset of test case that will be used to test the parts that have been changed in software. Finally, test suite prioritization identify the best order of test case that maximize some property, such as fault detection [YH10].

![Figure 1.2: Life of a Software System [AHKL93].](image)

In Figure 1.2, Agrawal et al. [AHKL93] describes a common example of a timeline during the life of a software system. As we can see, the execution of regression testing is a considerable fraction of the system’s lifetime. Unfortunately, regression testing cannot always be completed because of the frequent changes and updates of a system. When a program has been modified, it is indispensable to guarantee that the changes work correctly but also to ensure that the unmodified modules of the program have not been influenced by the modifications. It is extremely necessary because even small modifications, in one part of a program, may have a negative impact in other independent parts of the program. However the changed program can produce correct
Introduction

outputs with test cases particular constructed for that version. But it can produce incorrect outputs to other test cases which original program returns correct outputs. So, during the regression testing, the changed program is executed with all regression tests to check if it maintains the same functionalities present in the original program (except new changes) [AHKL93].

1.2 Motivation

Software development is an iterative process: there are new requirements, some need to be re-worked, removed, implement new features, etc. And the best existing bug prediction techniques in the literature predict that modifications on original software introduce bugs in 78% of times [KWZ08]. A software bug is the term used in informatics to describe a flaw, mistake, or fault in computer program that produces an incorrect or unexpected result. The results of bugs may be extremely serious.

Failures in software occur every day, and what is worse is that people are losing jobs and in some cases their liberty for software failures which can be preventable. Some examples of software failures in 2011:

**Computer system bugs cause Asian banking facilities’ downtime** “Computer system problems at one of Japan’s largest banks resulted in a nationwide ATM network of more than 5,600 machines going offline for 24 hours, internet banking services being shut down for three days.”

**Cash machine bug benefits customers by giving them extra money** “An Australian bank began giving out large sums of money from 40 cash machines across one city. Officials at the company said they were operating in stand-by mode, so could not identify the account balances of customers.”

**Bugs in social networking app for tablet just hours after delayed release** “Just hours after its release, this social networking sites’ long-awaited tablet app was already receiving reports about minor bugs from clicking through to pages via panel icons to problems posting comments.”

Other example happened in 2002: ‘A study commissioned by the US Department of Commerce’ National Institute of Standards and Technology concluded that software bugs, or errors, are so prevalent and so detrimental that they cost the US economy an estimated $59 billion annually, or about 0.6% of the gross domestic product” [2]. Software bugs is a consequence of bad quality politics or the nature of human errors in the programming task. So, it is very important testing the software. Testing is usually performed for the following purposes:

- **To improve quality.** Actually, computers and software are used in critical applications and the result of a bug can cause very serious damages.

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Introduction

- **For Verification & Validation (V&V).** Testing can be used such as metrics and actually is heavily used as a tool in the V&V process. People who make tests, can interpret and report the testing results, if the program works as defined or it does not work [Het88].

- **For reliability estimation.** Software reliability is an important measure for aspects related with software: it structure, of testing it has been subjected to. Based on an operational profile [Lyu96], testing can provide as a statistical sampling method to gain failure data for reliability estimation.

Therefore, when changes are made to the software, it is really important to re-execute the test to guarantee that features which already exist (before modifications) and new features introduced are working as expected. Normally, to re-test the software, regression test exercise all the test cases that were used to test the software before modifications were made. In practice, essentially on large software systems, re-execute all test case cannot be practical, mainly because the time and cost associated. In these situations testers at organization should decide which test cases to use in their regression testing [VF98].

As we can see in Figure 1.3, the worst regression approach mentioned in the literature, requires a many test cases to detect a minimum faults in the software. In the random approach, the number of test cases is proportional to the faults founded. The best approaches mentioned in the literature can already have a good ratio between number of detected faults and test cases. However, we think there is an opportunity for us to improve the existing regression techniques. The ideal approach with very few test cases immediately find all the theoretical faults in the software. Thus, is very hard and its necessary an ideal heuristic to do that, but this heuristic does not exist. So our approach focuses on trying to find more faults with fewer test cases as possible. Once the number of test cases increases, the curve of our approach will converge to the total number of failures (dashed line, hypothetical failures that may be in software).
1.3 Objectives

The adoption of regression testing techniques (minimization, selection and prioritization) remain limited, because testers does not have tools available which implement those techniques. For unit testing there are a number of frameworks based on the xUnit architecture [Mes07], and a weakness of regression testing is providing tools to support the studies that have taken in this area.

This is the first goal of this project, add to GZOLTAR the feature of unit testing. GZOLTAR [RA10] is an Eclipse plug-in [McC06] for automatic debugging, which integrates Zoltar [JAG09] core processing, along with other tools, to display powerful graphical visualizations representing the SUT, and indicating which component have higher failure probability. The main goal of these choice are to allow a developer to adopt this tool without much effort, by using the Integrated Development Environment (IDE) such as Eclipse, to test case management. Then, the objective is to implement several approaches for techniques of regression testing: minimization, selection, prioritization; which can reduce the effort time of re-test the software.

The main goal of this project is to develop an ecosystem where the developed can re-test and debug their software, with new latest studies in the field of regression testing and debugging software.

1.4 Concepts

**Definition 1.** Test Suite is a collection of test cases which purpose is to be utilized to test a software system.

**Definition 2.** Test case is a collection of settings or variables which every testers use to determine if a software system works as expected.

**Definition 3.** Minimum Set Cover (MSC) is the problem of finding the minimum sub collection (cover) of subsets whose union gives elements cover all the elements of main set.

1.5 Contribution

Overall, this thesis makes three contributions described as follow:

- We proposed a constraint solver-based novel technique for test suite minimization, selection and prioritization;

- The proposed technique has been implemented in the GZOLTAR toolset, this way providing an ecosystem for Debugging & Testing software programs;

- We have empirically analyzed the added value of our method using large-real world programs.
Introduction

The work proposed in this thesis has been disseminated as follows. A paper, covering Chapter 4, has been published in Investigação Jovem na Universidade do Porto (IJUP), 2012. Section 5.2 has been included in the paper submitted for publication in the International Journal of Creative Interfaces and Computer Graphics (IJCICG), 2012. Currently, we are preparing a submission to the top-tier International Symposium on Software Testing and Analysis (ISSTA), 2012, which will mainly discuss the proposed technique described in Chapter 3 as well as the results discussed in Chapter 4. Finally the toolset is going to be submitted for publication for a special edition on tools in the Automated Software Engineering Journal (ASEJ). Most publications are co-authored with Rui Abreu and André Riboira.

1.6 Document Structure

In this section will be presented this document structure. Apart from Introduction, this report has five more chapters.

Chapter 2 contains the state-of-the-art in regression testing field.

Chapter 3 presents our approach to test suite minimization, selection and prioritization on MSC problem.

Chapter 4 describes in detail the architecture of GZOLTAR Project (where RZOLTAR will be implemented).

Chapter 5 report the empirical evaluation on applying our approach to some open-source projects, and results about user studies.

Chapter 6 has the conclusions about this project, and also some ideas for future work.
Chapter 2

State of the Art

During the life-cycle of software development, software testing try to detect errors as early as possible to assure that modifications to existing software do not break the software. When software evolves test suites are frequently reused and updated. This resulting in a large test suite which can has some test cases considered redundant (requirements covered by these tests are also covered by other test cases). For re-executing large test suites is necessary resources and time, so it is important to develop techniques to minimize test suite by eliminating redundant test case, techniques to select test cases which are important to identify the parts of the SUT that have been modified, and techniques to prioritize test cases that find faults more earlier as possible, or maximize the rate of fault detection [TG05].

This chapter as organized as follow: Section 2.1 will be described the related work of technique for test suite minimization, in Section 2.2 will be described the studies of technique for test suite selection. In Section 2.3 will be described the studies of technique for test suite prioritization. Finally, the last Section 2.4 describe the perform tests that we conducted to choose between two testing frameworks.

2.1 Techniques for Test Suite Minimization

Technique to find and remove the redundant test case from the test suite is called as test suite minimization. Test cases become redundant because (1) their input/output relation is no longer meaningful due to changes in program, (2) these tests were developed for a specific program that has been modified or (3) their structure is no longer in conformity with the software coverage. Minimization or “test suite reduction” means a constant elimination, even so, the two concepts are related since all techniques act as a momentary subset of the test suite, in spite of only minimization techniques can always remove test cases [YH10].
More formally, following Harrold and Guppta [HGS93], test suite minimization is defined as follows:

**Definition 4.** (Test Suite Minimization Problem). Given: A test suite \( T \), a set of test requirements \( r_1, \ldots, r_n \), that must be satisfied to provide the desired testing coverage of the program, and subsets of \( T, T_1, \ldots, T_n \), one associated with each of the \( r_i \)'s such that any one of the test cases \( t_j \) belonging to \( T_i \) can be used to test \( r_i \)'s. Problem: Find a representative set, \( T' \), of test cases from \( T \) that satisfies all \( r_i \)'s.

The testing criterion is satisfied when every test requirement in \( r_1, \ldots, r_n \) is satisfied. A test requirement, \( r_i \), is satisfied by any test case, \( t_j \), that belongs to the \( T_i \), a subset of \( T \). Therefore, the representative set of test cases is the hitting set of the \( T_i \)'s. Furthermore, in order to maximize the effect of minimization, \( T' \) should be the minimal hitting set of the \( T_i \)'s [YH10]. Trying to find the minimal hitting set\(^1\) of a test suite that covers the same set of requirements by the original test suite is a NP-complete problem and this can be show by a polynomial time reduction from the MSC [GJ90] problem.

Trying to find the minimal test suite that covers the same set of requirements as the original one is a NP-complete problem, but can be solved in a polynomial time using the minimum set cover problem [GJ90]. NP-completeness of the test suite minimization problem encourages the usage of heuristics. Precedent work on test case minimization has advanced the state-of-the-art of heuristic approaches to the minimal hitting set problem, [Chv79, OPV95, HGS93, TG05, JG05, BMK04, HO09].

Chavatal [Chv79] proposes the usage of a greedy heuristic that chooses test case which covers almost all requirements about to be covered, until all requirements have been accomplished. This algorithm has been commonly seen as a solution to the minimum set-cover problem and an upper limit of how far apart it can be from the optimal size solution in the worst case that has been tested [Cor01]. However, a potential weakness of the greedy approach is that the early selection made by the algorithm can eventually be rendered redundant by the test cases subsequently selected and when there is a tie between multiple test cases, one test case is randomly selected [YH10]. In Table 2.1 Chavatal [TG05] consider that test suite and testing requirements to explain their approach. The greedy approach will select \( t_1 \) first as it satisfied the maximum number of testing requirements, and then continues to select \( t_2, t_3 \) and \( t_4 \). However, after the selection of \( t_2, t_3 \) and \( t_4 \), \( t_1 \) is considered redundant.

This heuristic only takes advantage of the implications among test cases in order to find out which test case became excessive while reducing a test suite [TG05].

Offutt, Pan, and Voaas [OPV95] dealt equally with the test suite minimization issue as the dual of the minimal hitting set problem, i.e. the set cover problem. Their heuristic can equally be looked at as a variation of the greedy approach to the set cover problem. Nonetheless, they implemented various test case orderings, rather than the fixed ordering in the ambitious approach.

\(^1\)A minimal hitting set is an hitting set such that none of its subsets is an hitting set.
Testing Requirements

<table>
<thead>
<tr>
<th>Test case</th>
<th>r₁</th>
<th>r₂</th>
<th>r₃</th>
<th>r₄</th>
<th>r₅</th>
<th>r₆</th>
</tr>
</thead>
<tbody>
<tr>
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<td>x</td>
<td>x</td>
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<td></td>
<td></td>
<td>x</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Table 2.1: Example test suite taken from Tallam and Gupta [TG05]. The early selection made by the greedy approach, $t₁$, is rendered redundant by subsequent selections, $t₂$, $t₃$, $t₄$.

Their empirical study pulled up techniques to a mutation-scored-based test case minimization, reducing the size of test suites by over 33% on average [YH10].

Another greedy heuristic, based on a determined number of test case covering specific demand, has been developed by Harrold, Gupta, and Soffa [HGS93] to choose a minimal subset of test case which covers the same set of demands as the un-minimized suite [TG05]. The proposal by Harrold et al. [HGS93] generates solutions which are always equally good or better than the ones computed by Chavatal [Chv79], although they have the worst case execution time of $O(|T| \times \max(|T_i|))$ [YH10]. In this case, $|T|$ represents the size of the original test suite, and $\max(|T_i|)$ represents the cardinality of the largest group of test cases among $T₁, \ldots, Tₙ$ [YH10]. Harrold et al.’s [HGS93] technique is more expensive than the ping-pong procedure presented by Offutt et al. [OPV95], and takes more information (specifically information as to which test cases satisfy each requirement). It appears that HGS technique is just as effective as OPV, and probably more efficient [OPV95].

The early selection made by the greedy algorithm is likely to be a weakness of the greedy approach, which can eventually provide redundant by the test cases subsequently selected. Tallam and Gupta [TG05] tried to overtake the weakness of the greedy approach by developing a concept lattice, a hierarchical clustering based on the relation between test cases and testing requirements [YH10]. Tallam et al. [TG05] heuristic, dubbed Delayed-Greedy, upgrades upon the prior heuristic by exploiting the implications and between the test cases and the implications between the coverage demands, were able to influence only independently from each other in the previous work [TG05]. Delayed-Greedy performs in three main phases: (1) apply object reductions (i.e., remove test cases which test requirements is subsumed by other test cases); (2) apply attribute reductions (i.e., remove test requirements that are not in the minimal requirement set); (3) build reduced test suite from the remaining test cases using a greedy method [HO09]. Empirical it was observed that, the test suite minimized by the ‘delayed-greedy’ approach were either the same size or smaller or even smaller than those which had been minimized by the classical greedy approach or by the HGS heuristic [YH10]. All these approaches ([Chv79], [OPV95], [HGS93], [TG05]) focus alone on single standard minimization problems. With this attitude, important dimensions of the issue are neglected and may bring forth test suites which are suboptimal when considering
such dimensions. For example, they can generate test suites which contain a reduced number of test cases, while having longer running time than other possible test suites. Or they may generate test suites that are minimal in terms of running time but have a considerably reduced fault detection ability [RHOH98], [WHLB97]. Furthermore, because even single-criterion problem are NP-complete, as demonstrated above, most of these techniques are based on approximated algorithms that make the problem manageable at the cost of computing answers that are suboptimal even for the simplified version of the minimization problem they attempt. Two studies by Rothermel et al. [RHOH98] and Wong et al. [WHLB97] investigated the boundaries of single-criterion minimization techniques. More precisely, these studies fulfilled experiments to estimate how minimized test suites are effective in terms of fault-detection ability. Their results exhibited that test suites minimized using single-criterion minimization technique might detect a lot less faults than the complete test suites.

The technique proposed by Jeffrey and Guppta [JG05] deals with the limitations of traditional single-criterion minimization techniques by taking in account several sets of testing demands (e.g., coverage of different entities) and introducing selective redundancy in the minimized test suites. Jeffrey et al. [JG05] illustrate their approach with an example (see Table 2.2) to generate a satisfactory minimized branch coverage test suite by keeping some redundant test cases in the reduced suite. And collect the coverage information for a secondary criteria, such as the all def-use pairs criteria, for all the test cases in the test suite $T$.

<table>
<thead>
<tr>
<th>Test Case</th>
<th>$B^T_1$</th>
<th>$B^F_1$</th>
<th>$B^T_2$</th>
<th>$B^F_2$</th>
<th>$B^T_3$</th>
<th>$B^F_3$</th>
<th>$B^T_4$</th>
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<td></td>
<td></td>
<td>X</td>
<td>X</td>
<td></td>
<td></td>
</tr>
<tr>
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<td></td>
<td>X</td>
<td>X</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>$t3$</td>
<td></td>
<td></td>
<td></td>
<td>X</td>
<td>X</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>$t4$</td>
<td></td>
<td></td>
<td></td>
<td>X</td>
<td></td>
<td></td>
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<td>X</td>
</tr>
<tr>
<td>$t5$</td>
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<td></td>
<td></td>
<td>X</td>
</tr>
</tbody>
</table>

Table 2.2: Brach coverage information for test cases in $T$ [JG05].

In the example presented by Jeffrey et al. [JG05], after inserting $t_1$ and $t_2$ in the minimized suite by HGS algorithm [HGS93], $t_3$ is described as redundant with respect to branch coverage since all the branches covered by $t_3$ are already covered by $t_1$ and $t_2$. Jeffrey et al. [JG05] verify if $t_3$ is also redundant with respect to the secondary criteria and in this case they found that $t_3$ covers the def-use pair $\alpha(4, 6)$ that is not covered by either $t_1$ or $t_2$. So, they do not identify $t_3$ as redundant and they add it to the minimized test suite. In their approach the minimized test suite at this point is constituted by $t_1$, $t_2$, and $t_3$. Next, either one of $t_4$ or $t_5$ can be chosen to cover the branch $B^T_4$. Jeffrey et al. [JG05] added $t_4$ to the constituted test suite and mark the requirement $B^T_4$ as coverage. At this point Jeffrey et al. [JG05] identified the test case $t_5$ as redundant with respect to branch coverage as well as with respect to the coverage of the secondary criteria. Therefore, the minimized test suite generated by their approach for this example is $\{t_1, t_2, t_3, t_4\}$. 
Jeffrey et al. [JG05] proceed an empirical evaluation using branch coverage as the first set of testing requirements and all-uses coverage information obtained by data-flow analysis. They compared their results to two versions of the HGS heuristic, based on branch coverage and def-use coverage. Therefore, the results showed by Jeffrey et al. [JG05] demonstrate that, although their technique returns larger test suites, the fault-detection adequacy was better preserved compared to single-criteria versions of the HGS heuristic [YH10]. However, in spite of their approaches improve existing techniques, it continues to be an heuristic, approximation [HO09].

An improved attempt at overtaking the limitation of existing approaches is the technique that Black, Melachrinoudis, and Kaeli, [BMK04] proposed which consists on a two criteria variant of single-criterion traditional test suite minimization attempts and computes optimal solutions using an integer linear programming solver [HO09]. A limitation of this approach is that fault detection is reputable concerning a single fault (rather than several faults), and accordingly there may be limited confidence that the limited suite be useful in detecting several other faults. Also, the approach is limited in typed of minimization problems it can handle [HO09].

Hsu and Orso [HO09] such as Black et al. [BMK04] also took in consideration that the use of an Integer Linear Programming (ILP) solver with multi-criteria test minimization. Hsu et al. [HO09] demonstrate that the majority of minimization techniques proposed have two limitations: they perform minimization based upon a single criterion and produce approximated suboptimal solution. Therefore, they extended the work of Black et al. [BMK04] by comparing several heuristics for a multi-criteria ILP formulation: the weighted-sum approach, the prioritized optimization and a hybrid approach. In prioritized optimization, the user assigns a priority to each given criteria. After optimizing for the first criteria, the outcome is added as a constraint, at the same time as optimizing for the second criteria, and so on. However, one possible weakness shared by these approaches is that they require additional input from the user of the technique in the forms of weighting coefficients or priority assignment, which might be biased, unavailable or costly to provide [YH10].

2.2 Techniques for Test Suite Selection

Test case selection, or the Regression Testing Selection (RTS) problem, is basically similar to the test suite minimization problem (defined in Section 2.1). The two technique have the same problems about choosing a subset of test cases from the test suite. The main difference between these two approaches in literature is the focus against the changes in the SUT. While test case selection techniques try to minimize the cardinality of a test suite, the majority of selection techniques are modification-aware. That is, the selection is not only temporary (i.e. specific to the current version of the program), but also focused on the identification of the modified modules of the new version of program. Test cases are selected because they are relevant to the changed parts of the SUT, which regularly involves a while-box static analysis of the program code [YH10].
More formally, following Rothermel and Harrold [RH96], selection problem is defined as follows:

**Definition 5.** (Test Case Selection Problem). Given: The program, $P$, the modified version of $P$, $P'$ and a test suite, $T$.
Problem: Find a subset of $T$, $T'$, with which to test $P'$.

Based on Rothermel’s et al. [RH96] formulation of the problem, it can be said that test case selection techniques for regression testing focus on identifying the modification-traversing test cases in the given test suite. The details of the selection procedure differ according to how a specific technique defines, seeks and identifies modifications in the SUT. Various techniques have been proposed using different criteria including Integer Programming (IL) [FRC81], program slicing [HGS93], dynamic slicing [AHKL93], graph-walking [RH97], textual difference in source code [VF98], and modification detection [CRV94].

Fisher, Raji, and Chruscicki [FRC81] developed an approach that uses IL to try resolve the selection problem. One weakness in Fischer’s approach is its inability to deal with control-flow changes in $P'$. The test case dependency matrix, $a_{11}, \ldots, a_{mn}$, depends on the control-flow structure of the SUT. If the control-flow structure changes, the test case dependency matrix can be updated only by executing all the test cases, which negates the point of applying the selection technique [YH10].

The criteria for testing data flow, is based on the tracking of a variable values through a program. These are recognized by the variable’s names and definition locations, but when a variable name denotes multiple values, they can be tough to track. This problem shows up with the use of arrays and pointers [Tah92]. Harrold, Gupta, and Soffa [HGS93] applied program slicing technique to recognize definition-use pairs which are influenced by a code modification. Using slice technique allows identification of definition-use pairs in need to be tested without representing a complete data-flow analysis, often very expensive. One impotence that all data-flow analysis based test case selection technique share, is the fact that they are not able to detect changes which are not related to data-flow change [YH10]. For instance, if $P'$ has new procedure calls without a parameter, or changed output statements which have no variable uses, data flow techniques might not choose test cases executing these.

Agrawal, Horgan, Krauser, and London [AHKL93] presented a family of test case selection techniques supported by different program slicing technique. An execution slice of a program concerning a test case is something which is usually referred to as an execution trace for it is the set of statements executed by the given the test case. A dynamic slice of a program concerning a test case is the group of statements in the execution slice that influences an output statement. An execution slice is able to contain statements that do not affect the program output, so a dynamic slice is a subset of an execution slice. To make a more precise selection, Agrawal et al. suggested additional slicing criteria: a relevant slice and an approximate relevant slice. An relevant slice of a program concerning test case is the dynamic slice concerning the same test case together with
all the predicate statements in the program that, if analyzed in a different way, could have been the cause for the program to produce a different output. An approximated relevant slice is a more preservative approach to include predicates which could have caused a different output; for it is the dynamic slice including all the predicate statements in the execution slide [YH10]. Agrawal et al. built, in the first place, their technique on cases with restricted modifications to those which do not change the Control Flow Graph (CFG) of the program that is being tested. For as long as the CFG of the program continues to be the same, their technique is secure and can be looked at as an improvement over Fisher’s IL approach [FRC81] in its whole. Slicing erases the necessity to formulate the linear programming issue, decreasing the required effort from the tester [YH10].

The technique developed by Rothermel and Harrold [RH97] bases itself on the idea of CFG to perform and compare the older and newer versions of a program. Their algorithm constructs graphs representing control dependence for a program and its modified version, and uses these graphs to identify tests that are potentially revealing and tests that cannot possibly expose errors. Their algorithm detects regions of code that differ in the two versions of the program, and selects for retest all tests that traverse these regions. Harrold et al. concluded this is a safe technique, able to select a pretty precise subset of the test cases. It was implemented in a prototype research tool named DejaVu.

Volkolos and Frankl [VF98] suggested a selection technique based upon the textual difference between the source code of two versions of SUT. They identified parts which had been modified of SUT by applying the diff Unix tool to the source code of a different version. The source code was previously processed into canonical forms to remove the impact of cosmetic differences. Although their technique operates on a different representation of SUT, its behavior is very similar to the CFG-based graph walk approach [YH10]. After running various experiments, they concluded, concerning the time needed for the analysis, it appears based on their data, that textual differencing is a lot faster than the technique previously developed by Harrold et al. [RH97].

Chen, Rosenblum, and Vo [CRV94] introduced a testing framework called TestTube, which utilizes a modification based technique to select test cases. TestTube partitions the SUT into program entities, and monitors the execution of test cases to establish connections between test cases and the program entities that they execute. TestTube also partitions P’ into program entities, and identifies program entities that are modified from P. All the test cases that execute the modified program entities in P should be re-executed [YH10].

Chen et al. explained the idea behind TestTube in Figure 2.1. In the Figure 2.1, the boxes represent subprograms and circles represent variables. The arrows represent static and dynamic dependency relationship (e.g., variable references and function calls). The shaded entities were modified to create a new version of the SUT. Using s simple technique such as retest-all, all three test units must be rerun in order to test the changes. However, Chen et al. concluded that relationship between the test units and the entities they cover, it is possible to eliminate test unit 1 and 2 from the regression testing of the new version and rerun only test unit 3.

TestTube is less precise [YH10] than Rothermel et al. [RH97] tool, DejaVu, but more resistant in analyzing large software systems [VF98]. One weakness of TestTube is pointer handling. By
including variable and data types as program entities, TestTube requires that all value creations and manipulations in a program can be inferred from source code analysis. This is only valid for languages without pointer arithmetic and type coercion.

### 2.3 Techniques for Test Suite Prioritization

Prioritization techniques order the test cases based on defined criteria such that the test cases with a low chance of finding defects are executed at the end, and that test cases with a high probability are executed first [MT08]. This technique provides to testers the possibility to order their test cases so that test cases with large priority (according to some criterion), are executed first and after test cases with less priority are executed in the regression testing process. For example, testers might wish to reorder test cases in an order that achieves code coverage at the fastest rate possible, exercises subsystems in an order that reflects their historically demonstrated propensity to fail [RUCH01]. More formally, following Rothermel and Harrold [RH96], prioritization problem is defined as follows:

**Definition 6.** (Test Case Prioritization Problem). Given: A test suite, $T$, the set permutations of $T$, $PT$, and a function from $PT$ to real numbers, $f : PT \rightarrow \mathbb{R}$.

Problem: To find $T' \in PT$ such that $(\forall T'')(T'' \in PT)(T'' \neq T')[f(T') \geq f(T'')]$.

Average Percent of Fault-Detection (APFD) is commonly used to evaluate test case prioritization techniques. The APFD value for $T'$ is calculated as follows [EM02]:

$$\text{APFD} = 1 - \frac{TF_1 + \ldots + TF_m}{nm} + \frac{1}{2n}$$

Maximization of APFD would be possible only when every fault that can be detected by the given test suite is already know. This implies that all test cases have already been executed,
which does the need to prioritize. **APFD** is computed after the prioritization only to measure the performance of the prioritization technique [YH10].

Various approaches have been proposed using different techniques and criteria, [RUCH01, DRK04, LP03, KP02, MT08].

Rothermel, Untch, Chu, and Harrold [RUCH01] describe their approach with nine different test case prioritization techniques: untreated (no prioritization), random (randomized ordering), optimal (ordered to optimize rate of fault detection), statement-total (prioritize in order of coverage of statements), statement-additional (prioritize in order of coverage of statements not yet covered), branch-total (prioritizes in order of coverage of branches), branch-additional (prioritize in order of coverage of branches not yet covered), FEP-total (prioritize in order of total probability of exposing faults), FEP-additional (adjusted to consider effects of previous test cases).

To illustrate the **APFD** measure obtained with Rothermel et al. [RUCH01] approach, consider an example program with 10 faults and a test suite of five test cases, A through E, with fault detecting abilities, as shown in Table 2.3.

<table>
<thead>
<tr>
<th>Test</th>
<th>Faults</th>
</tr>
</thead>
<tbody>
<tr>
<td>A</td>
<td>x</td>
</tr>
<tr>
<td>B</td>
<td>x</td>
</tr>
<tr>
<td>C</td>
<td>x</td>
</tr>
<tr>
<td>D</td>
<td>x</td>
</tr>
<tr>
<td>E</td>
<td>x</td>
</tr>
</tbody>
</table>

Table 2.3: Test suite and faults exposed [RUCH01]

Rothermel et al. first consider the test cases in order A-B-C-D-E to form a prioritized test suite $T_1$. After running test case A, two of the 10 faults are detected; thus, 20% of the faults have been detected after 0.2 of test suite $T_1$ has been used. After running test case B, two more faults are detected and, thus 40% of the faults have been detected after 0.4 of the test suite has been used. The **APFD** is 50% percent in this example. When the order of test cases in changed to E-D-C-B-A, yielding test suite $T_2$, a “faster detecting” suite than $T_1$ with an **APFD** of 64%. Changing to C-E-B-A-D, by inspection, they concluded this ordering results in the earliest detection of the most faults and illustrates an optimal ordering with an **APFD** of 84%. Their empirical results concluded that random prioritization could exploit the weakness of untreated test cases in several cases [YH10].

Do, Rothermel, and Kinneer [DRK04] applied the most popular unit testing framework, JUnit, to coverage-based prioritization technique. The results show that prioritized execution of JUnit test cases improved the detection of faults. They finding that random prioritization sometimes resulted in an higher value of **APFD** than the untreated ordering, i.e., in the order of creation, newer unit tests are executed later. With the difficulty to known what tests expose a fault, test case
prioritization techniques depend on surrogates, assuming that early maximization of a surrogate criteria will result in maximization of earlier fault detection. In a controlled-regression-testing environment, the result of prioritization can be measured by executing test cases according to the fault detection rate [YH10].

Leon and Podgurski [LP03] developed a prioritization techniques that integrate coverage-based prioritization with distribution-based prioritization. This hybrid approach is based on the observation that basic coverage maximization achieve a reasonably performs when as compared to repeated coverage maximization. Repeated coverage maximization, after reaching 100% coverage, starts again from 0% of coverage repeating the prioritization of test cases. In the other hand, basic coverage maximization stops prioritizing when 100% coverage is accomplished. Leo et al. observed that the fault-detection rate of repeated coverage maximization is not as high as that of basic coverage maximization. This motivated them to consider a hybrid approach that first prioritizes test cases based on coverage, then swap to distribution-based prioritization as soon as the basic coverage maximization is accomplished. Leo et al. observed that the fault-detection rate of repeated coverage maximization is not as high as that of basic coverage maximization. This motivated them to consider a hybrid approach that first prioritizes test cases based on coverage, then swap to distribution-based prioritization as soon as the basic coverage maximization is accomplished. They considered two different distribution-based technique: one-per-cluster and failure-pursuit. The one-per-cluster approach choose one test case from each cluster, and prioritizes them according to the other of cluster creation during the clustering. The failure-pursuit approach act equivalently, but it adds the $k$ closest neighbors of any test case that reveal a fault. They [LP03] concluded that distribution based techniques can be as efficient or more efficient for revealing defects than coverage-based technique, but two techniques are also interconnected in order that they find different faults.

Kim and Porter et al. [KP02] proposed a history-based approach to prioritize test cases that are already selected by RTS. If the number of test cases selected by an RTS technique continue to high, or if the execution costs are too high, then the selected test cases may have an addition prioritization. After all, the relevance to the recent change in SUT is deduced by the use of an RTS technique. Kim et al. focus on the execution history of each test case, extracting this information from statistical quality control. Kim et al. define Last Recently Used (LRU) prioritization by using test case execution history as $H_c$ with $\alpha$ value that is as close to 0 as possible. The empirical evaluation showed that the LRU prioritization approach can be competitive in a severely constrained testing environment, i.e. when executing all test cases selected by an RTS technique can not be done [YH10].

Mirarab and Tahvildari [MT08] introduced a probabilist approach to prioritization problem which utilizes Bayesian Networks (BN) and a feedback mechanism. BN [Pea88] is a directed acyclic graph consisting of three elements: nodes representing random variables, arcs representing probabilistic dependencies among those variables, and a Conditional Probability Distribution Table (CPT) for each variable, which includes the conditional probabilities of outcomes of its variable given the valued of all its parents. BN is used to predict the probability of each test case finding a fault using different several sources of information. Mirarab et al. conduct an extensive empirical study of evaluate the performance of the BN approach. The controlled experiments compare several different realizations of the proposed approach, and using mutation technique which can provide large number of faults. The objective of their controlled experiments is to compare
different implementations of the proposed approach and to understand the effects of its underlying parameters. They concluded that most of the other prioritization techniques from the literature are reported to perform more efficiently when used in conjunction with feedback [EM02].

2.4 Unit Testing Framework

For the development of this project was necessary to find a framework for the execution of automated unit test. A important benefit of such tools is their capability to execute unattended (e.g., to run overnight or over weekend), providing to the testing task a significant gain in productivity. Automated tools can also provide more confidence in the SUT by allowing more tests to be executed in the same time as that taken for an equivalent manual test [Wat01]. And the chosen framework had allows easy integration with GZOLTAR architecture, in particular with JaCoCo [Hof11a] (Java-based API that offers code coverage capabilities) module. So, for comparison we chose two frameworks: JUnit and TestNG.

JUnit\(^2\) is the Java version of popular xUnit framework and it can be describe as the father of automated unit test, where frameworks like NUnit and PHPUnit its based. JUnit like others frameworks exist for other programming languages and this show how can versatile the framework can be.

TestNG (the NG stands for Next Generation)\(^3\) is a framework for automated unit test too, inspired in JUnit and NUnit but with some improvements. It introduced some new features like groups of tests, parallel testing, etc. In next sections we present more details about differences between JUnit and TestNG.

2.4.1 Features

In Java, the most popular frameworks for unit test are JUnit and TestNG and both are very similar in features. Both make easy the test task making it practical and simple and also have a vast community that supports its continued development. We can see the differences between frameworks just in Core design. JUnit was always a framework directed to unit test, was developed to make easy the test of simple objects, and it does this very efficient. Otherwise, TestNG was developed to raise the level of testing (unit, functional, end-to-end, integration, etc) and therefore has some features not available in JUnit.

In Table 2.4 we can see a brief resume about the most important features present in both frameworks.

\(^3\)Cédric Beust. TestNG Homepage [http://testng.org/doc/index.html], 2012.
State of the Art

<table>
<thead>
<tr>
<th>Feature</th>
<th>JUnit 4.9</th>
<th>TestNG v5.14.10</th>
</tr>
</thead>
<tbody>
<tr>
<td>Annotation</td>
<td>YES</td>
<td>YES</td>
</tr>
<tr>
<td>Supported by Eclipse</td>
<td>YES</td>
<td>YES</td>
</tr>
<tr>
<td>Parallel test</td>
<td>YES</td>
<td>YES</td>
</tr>
<tr>
<td>Dependence between tests</td>
<td>NO</td>
<td>YES</td>
</tr>
<tr>
<td>Groups of tests</td>
<td>YES</td>
<td>YES</td>
</tr>
<tr>
<td>Objects</td>
<td>EasyMock</td>
<td>DataProvider</td>
</tr>
<tr>
<td>Parametrized tests</td>
<td>YES</td>
<td>YES</td>
</tr>
<tr>
<td>Threads</td>
<td>NO</td>
<td>YES</td>
</tr>
<tr>
<td>First Release</td>
<td>1997</td>
<td>2004</td>
</tr>
</tbody>
</table>

Table 2.4: Features comparison between JUnit and TestNG frameworks

After the version 1.5 of Java, the platform has support to *Annotations*. *Annotations* is a very special form of syntactic meta-data which can be added to our Java code, and allow to annotate packages, class, methods, parameters, variables. TestNG support this features since the beginning.

The most significant difference between JUnit e TestNG is dependencies between tests. TestNG support this feature naively and JUnit not. This implies that beyond simple unit testing, with TestNG we can also perform integration tests.

If we have some code that will create threads on execution, we need TestNG to test them. TestNG support threads test but JUnit not, because it run every tests on one single thread. However, JUnit is in the development environment for years, while TestNG appeared only in 2004.

### 2.4.2 Performance

As we can see, both frameworks are very identical, but until now we have not considered the parameter performance. To test the performance of both frameworks, we developed a trivial project called Calculator Project (see Section 2.4.2.1).

In every experience of project was measured the execution time of test suite for every framework, JUnit and TestNG. During the experiences that test suite was increased in size.

#### 2.4.2.1 Calculator Project

Calculator Project is a simple project developed in Java that simulates a normal calculator with functions like: add, subtract, module, maximum, etc. To test the functionalities of Calculator first we write ten tests, one test for every feature. Afterwards we replicate the test in order to increase the size of test suite. In Table 2.5 we can see the average results for each framework and the size of test suite. For every details about experiences and its results, consult Appendix B.
As we can see, for suites test with size more than 500, the performance of TestNG framework becomes unacceptable. While JUnit framework maintain quite low execution times, even with 1000 tests.

2.4.3 Summary

For automated unit testing we need to choose a framework to do that, so we evaluated JUnit and TestNG. We discuss the features differences between both frameworks and compare them about performance. Although the TestNG has some something innovative in the area, enabling the creation of high level testing (integration testing, functional, etc.) but your performance is not satisfactory. One goal of this project is minimizing the time of test phase, without affecting the confidence in testing and in project quality, so the framework chosen should run as fast as possible. We concluded the best option for this project is JUnit.
State of the Art
Chapter 3

Test Suite Minimization, Selection, and Prioritization

A change in a program causes a test case to become obsolete by removing the reason for the test case’s inclusion in the test suite. A test case is redundant if other test cases in the test suite provide the same coverage of the program. Thus, because obsolete and redundant test cases, the test suite has a needless test cases which make the test suite to enlarge as changes are made. Reducing the size of the test suite decreases the effort of maintaining the test suite and the number of test cases that should be rerun subsequent modification in the software. Therefore, it is important to determine a minimum set of test cases that provides the same coverage of the changed parts of the program. This selective technique, choose the tests from the old test suite that are necessary to test new and old features of the program. Another technique for supporting regression testing is prioritization technique. The test cases presented in the test suite can be ordered based on certain criteria such that the cases with a higher probability of finding faults are executed earlier. These techniques help testers to adjust their time and budget by running as many test cases as they can afford in a given period of time. In this chapter, we present a new approach to test suite minimization, selection and prioritization on MSC problem. The process of selecting a MSC of test cases, such that all feasible required components of a program are covered, can be modeled by a Coverage Matrix (explained in the next section). Such matrix stores the relation between execution of test cases and involvement of components, which in turn can be mapped to several constraints.

To the best of knowledge this approach has not been presented before and has proven to have a significant reduction of suite tests, maintaining the same percentage of reliability (see Chapter 5).

The reminder of this chapter is organized as follows. We start by introducing the coverage matrix, followed by some concepts about MSC. Subsequently, transform the coverage matrix into
constraints is described, followed by how to solve the Constraint Satisfaction Problem (CSP) and then the time/space complexity are presented. Finally, a summary of this chapter is given.

3.1 Coverage Matrix

White-box software testing methods examines the physical structure of a program, highlighting certain structural components of the code which are examined during the testing process. Each test case from the test suite, when run through the program, will cover a subset of the total set of structural components. By tracking which components each test case activate (covers), a \(N \times M\) binary matrix \(A\), can be created (see Figure 3.1).

\[
\begin{bmatrix}
    a_{11} & a_{12} & \cdots & a_{1M} \\
    a_{21} & a_{22} & \cdots & a_{2M} \\
    \vdots & \vdots & \ddots & \vdots \\
    a_{N1} & a_{N2} & \cdots & a_{NM}
\end{bmatrix}
\]

Figure 3.1: Coverage Matrix, \(N\) means tests executions, \(M\) means a component of SUT, and \(a_{ij}\) means coverage.

In Figure 3.1, the entries cross-reference test requirements and tests. Columns correspond to \(M\), different components (source code statements in the context of this manuscript) of a software program, and lines represent an execution of a test case. An element \(a_{ij}\) is equal to 1 if and only if component \(m_j\) is covered when the test \(t_i\) is executed:

\[
\omega(t_i, m_j) = (a_{ij} == 1 \ ? \ true \ : \ false)
\] (3.1)

That is, while a test may be designed to cover a specific component, other components may be covered incidentally. So, the result of interception between test and component is returned by function \(\omega(t_i, m_j)\), Equation 3.1.

The minimum set coverage method as described in the next section performs such an analysis and produces a reduced test suite which still provides 100% test coverage of components.

3.2 Minimum Set Coverage

The MSC problem is one of the class of NP-hard problems which has applicability to the scope of software testing [GJ90].

Let \(S\) be a collection of \(N\) non-empty sets \(S = \{s_1, \ldots, s_N\}\). Each set \(s_i \in S\) is a finite set of components (source code statements in our case), where each of the \(M\) components is represented
by \( m_j, \ j \in \{1, \ldots, M\} \), so, formally, \( s_i = \{m_j \mid \omega(t_i, m_j) = 1\} \). A minimum set coverage of \( S \) is a set \( T' \) such that:

\[
\forall s_i \in S, s_i \cap T' \neq \emptyset \land \nexists T'' \subset T' : s_i \cap T'' = \emptyset
\]

i.e., each member of \( S \) has at least one component of \( T' \) as a member, and no suitable subset of \( T', T'' \), is a coverage set. During the construction of the minimum set, each test should be analyzes to determine the component which it covers and all \( t_i \) in \( T' \), must cover at least one component:

\[
\forall t'' \in T'', \ \omega(t'', m) = true
\]

There may be several minimum set coverage for \( S \), which constitutes a collection of minimum set coverage \( T = \{t_1, \ldots, t_k, \ldots, t_{|T|}\} \). In order to maximize the effect of minimization, \( T'' \) should be the minimal hitting set of the \( T_i \)’s.

As an example, consider the coverage represented by the matrix in Figure 3.2.

![Matrix example](image.png)

Figure 3.2: Matrix example, with four tests (lines) and three components (columns). E.g., the component \( m_2 \) is activated when set \( \{t_1, t_3\} \) is executed.

In coverage matrix (see Figure 3.2), the global set is \( S = \{\{t_1, t_2\}, \{t_1, t_3\}, \{t_4\}\} \), where, \( m_1 \) is covered by set \( \{t_1, t_2\} \), \( m_2 \) covered by set \( \{t_1, t_3\} \), and \( m_3 \) covered by set \( \{t_4\} \).

A brute-force approach to compute the collection \( T' \) of minimum set coverage for \( S \), would be to iterate through all possible component combinations to (1) check if it is a coverage set, and (2) whether it is a coverage set, if it is minimal, i.e., not subsumed by any other set of lower cardinality. As all possible combinations are checked, the complexity of such an approach is \( O(2^M) \). For the example above, the following sets would be checked: \( \{t_1\}, \{t_2\}, \{t_3\}, \{t_4\}, \{t_1, t_2\}, \{t_1, t_3\}, \{t_1, t_4\}, \{t_2, t_3\}, \{t_2, t_4\}, \{t_3, t_4\}, \{t_1, t_2, t_3\}, \{t_1, t_2, t_4\}, \{t_1, t_3, t_4\}, \{t_2, t_3, t_4\}, \{t_1, t_2, t_3, t_4\} \) to find out that just set \( \{t_1, t_4\} \) or \( \{t_2, t_3, t_4\} \) are necessary to coverage all components.

### 3.3 Map Coverage Matrix into Constraints

Identifying MSC of a collection of sets is an important problem in many domains, such as Air Crew Scheduling, in which a set of flights must be covered by a collection of available crew members [Wil99], where the MSC are the solutions for the scheduling problem.
As explained in the previous Section, brute-force algorithms have a cost that is exponential in the number of components. We take however an off-the-shelf CSP toolkit, namely MINION, to solve the MSC. We use a constraint solver to compute the MSC solutions since current toolkits already solve large CSPs problems with up to million of variables (components) and million of constraints. In this Section we present our approach: transform the coverage matrix into constraints, aimed to increase search efficiency. The Section 3.4 describes how to solve the constraints using the constraint solver MINION.

Algorithm 1 Map Coverage Matrix into Constraints

1: **Input:** Matrix $A$, number of components $M$, number of test cases $T$
2: **Output:** Conjunctions of disjunctions $C$
3: $C \leftarrow \emptyset$  \hspace{1cm} $\triangleright$ empty conjunction
4: **for all** $i \in \{1 \ldots M\}$ **do**
5: $C' \leftarrow \emptyset$  \hspace{1cm} $\triangleright$ empty disjunction
6: **for all** $j \in \{1 \ldots T\}$ **do**
7: if $a_{ij} = 1$ **then**
8: $C' \leftarrow C' \lor j$
9: **end if**
10: **end for**
11: $C \leftarrow C \land (C')$
12: **end for**

The key idea, behind our approach is breaking the problem up into a set of distinct constraints (see Algorithm 1), each of which have to be satisfied for the problem to be solved.

For the example (Figure 3.2), to ensure that component $m_1$ is covered, the test $t_1$ or the test $t_2$ needs to be executed:

$$c_1 = \{t_1 \lor t_2\}$$

To coverage the component $m_2$, the test $t_1$ or test $t_3$ are essential, so the mapping is

$$c_2 = \{t_1 \lor t_3\}$$

To coverage the component $m_3$, it is only required to execute the test $t_4$

$$c_3 = \{t_4\}$$

So, the final solution is the concatenation of all equations

$$C = \{ \{t_1 \lor t_2\} \land \{t_1 \lor t_3\} \land \{t_4\} \}$$
3.4 Solve Constraint Satisfaction Problem

Using constraint satisfaction as a global framework, concede the possibility to encode several real world problems, including formal verification, vehicle routing and scheduling. A CSP \( \text{CSP} \) can be expressed in a set of variables that should be attributed values from their domains in such a way that a set of constraints must be satisfied. Generally and such as MSC, searching a solution of a CSP is an NP-complete problem. Therefore, several researchers have been studying this field to find restricted classes of CSPs that admit polynomial time algorithm.

Since coverage matrix is a boolean matrix, it can be converted into boolean CSP. Boolean CSPs include as special cases some NP-complete problems, such as SAT. SAT is the prototypical NP-complete problem. However, we can approximate solutions that satisfy the maximum number of clauses in polynomial time.

In this Section we present our solution to the CSP, using the state-of-art solver MINION \([\text{GJM06]}\) and Trie structure.

3.4.1 MINION

MINION\(^1\) is a general-purpose constraint solver, with an expressive input language based on the common constraint modeling device of matrix models. Experimental results show that MINION typically runs between 10 and 100 times faster than state-of-the-art constraint toolkits such as ILOG Solver\(^2\), ECLiPSe\(^3\), and GeCode\(^4\) on huge and hard problems. For little problems or instances where solutions are discovered with a simple search, gains are not so well \([\text{GJM06]}\).

From the point of view of the user, MINION is a black box which provides few options and is an open source project that continue under development. A individually characteristic of this CSP solver is the fact that variables are represented at hardware level to optimize the solving algorithm (backtracking) \([\text{NPW08]}\). It supports four individually-optimised integer domain types: 0/1 domains, usually used for logical expressions; bounds domains, which keep only the lower and upper value of the domain; sparse domains, where domain values need not be adjacent, e.g. \(\{2, 7, 11\}\); and discrete domains, originally the lower and upper bound is defined but support the elimination of valued from between the bounds \([\text{GMR07]}\).

Considering the restriction of Section 3.3 it can be easily converted into constraints in MINION syntax:

MINION 3

**VARIABLES**

\(^1\)MINION Homepage http://minion.sourceforge.net/, 2012.
\(^3\)ECLiPSe Homepage http://eclipseclp.org/, 2012.
Test Suite Minimization, Selection, and Prioritization

BOOL t1
BOOL t2
BOOL t3
BOOL t4

**SEARCH**

VARORDER [t1, t2, t3, t4]
PRINT ALL

**CONSTRAINTS**

watched-or({eq(t1,1), eq(t2,1)})
watched-or({eq(t1,1), eq(t3,1)})
watched-or({eq(t4,1)})

**EOF**

Briefly, in this model there are three boolean variables, each variable is identified by ‘\(t_i\)’, for \(i \) in \(1 \ldots (N - 1)\) which represent test cases. In constraints section appears the logical constraint watched-or for formalizing all disjunctions. Assuming that the priorities of components and the complexity of test are uniform, MINION produces five possible sets:

1. \{t_1, t_4\}
2. \{t_1, t_2, t_4\}
3. \{t_1, t_3, t_4\}
4. \{t_2, t_3, t_4\}
5. \{t_1, t_2, t_3, t_4\}

Analyzing the result returned by MINION, the set \{t_1, t_2, t_3, t_4\} is clearly selected as a valid solution, because it is the selection of all test cases in the original suite. The first set, provided by MINION, is the minimization of original set, from four to two test cases: test number 1 and 4. The result coverage matrix can be found in Figure 3.3.

\[
\begin{array}{ccc}
  & m_1 & m_2 & m_3 \\
 t_1 & 1 & 1 & 0 \\
 t_4 & 0 & 0 & 1 \\
\end{array}
\]

Figure 3.3: Matrix coverage for first set, \{t_1, t_4\}, provided by MINION.

This reduced matrix (Figure 3.3), containing only two tests, obviously has the same complete test coverage as the original matrix. However, if test \(t_1\) were omitted from the suite, then three
components would not be covered by the remaining test \((m_1 \text{ and } m_2)\). Similarly, the omission of test \(t_4\) would leave component \(m_3\) uncovered.

Likewise, for the other three sets the coverage matrix is described in Figure 3.4.

\[
\begin{bmatrix}
1 & 1 & 0 \\
1 & 0 & 0 \\
0 & 0 & 1
\end{bmatrix}
\]

(a) Matrix coverage for first set, \{\(t_1, t_2, t_4\)\}.

\[
\begin{bmatrix}
1 & 1 & 0 \\
0 & 1 & 0 \\
0 & 0 & 1
\end{bmatrix}
\]

(b) Matrix coverage for second set, \{\(t_1, t_3, t_4\)\}.

\[
\begin{bmatrix}
1 & 0 & 0 \\
0 & 1 & 0 \\
0 & 0 & 1
\end{bmatrix}
\]

(c) Matrix coverage for third set, \{\(t_2, t_3, t_4\)\}.

Figure 3.4: Matrix coverage for sets: \{\(t_1, t_2, t_4\)\}, \{\(t_1, t_3, t_4\)\}, and \{\(t_2, t_3, t_4\)\}.

To filter the results provided by MINION (eliminate the redundant set) was used a special data structure, dubbed Trie, explained in next subsection.

### 3.4.2 TRIE

The term TRIE [Fre60] appeared from retrieval. According with the etymology, the creator, Edward Fredkin, pronounces it \(/^\text{tri}/\) “tree”. However, other authors pronounce \(/^\text{traI}/\) “try”.

In computer science, a TRIE is a tree data structure (typically ordered) which can be used to keep an associative array where the keys are commonly strings. The key idea is that strings with a common prefix share nodes and edges in the tree. Each node can have at most \(k\) children, where \(k\) is one more than the size of the alphabet, and each edge is classified either with a character from the alphabet or a appropriate terminating character. The root node has a child for each distinct first character, \(\alpha\), in the set of strings, and the edge connecting the two is classified with \(\alpha\). Each internal node \(n\) has a child for each string that has a prefix corresponding to the characters on the edges in the path from the root to \(n\), read in order. Searching for a string in a trie (the main operation useful for supporting a table constraint), is \(O(d)\) where \(d\) is the length of the string [GJM07].

The main advantages of TRIE:

- Ease with handling sequences of several lengths;
- Add and delete can be facility achieved;
- Speed of storage and access;

The main drawback is the relative storage space requirement, but this inefficiency is not problematic when the store is very large [Fre60].

To illustrate this data structure consider, again, the previous example in Figure 3.2 and the output provide by MINION:
Test Suite Minimization, Selection, and Prioritization

1. \{t1, t4\}
2. \{t1, t2, t4\}
3. \{t1, t3, t4\}
4. \{t2, t3, t4\}
5. \{t1, t2, t3, t4\}

First TRIE structure starts with an empty node and then the first set, \{t1, t2\} is inserted (see Figure 3.5).

![Trie Diagram](image)

Figure 3.5: TRIE Example: empty TRIE (left), added the string “t1” (center), and the final TRIE, after added the string “t4” (right)

The set \{t1, t2\} can be inserted with success, because elements “t1” and “t4” do not exist in TRIE structure. But if trying to insert the others sets \{t1, t2, t4\}, \{t1, t3, t4\}, or \{t1, t2, t3, t4\} it cannot do that, because all these sets have at least one element that already exist in TRIE structure. So, with TRIE structure it can be remove non minimal sets, that have other sets inside. Using TRIE, the solution for MSC of example described in Figure 3.2 are \{t1, t2\} and \{t2, t3, t4\}.

3.5 Complexity Analysis

To measure the complexity of our approach we show the time and space complexity.

Time Complexity

To find a MSC, all test cases need to be executed in order to obtain the coverage matrix. Without loss of generality, test cases are assumed to take the same amount of time to execute. Thus, the time complexity for this phase is $O(|T|)$ where $|T|$ is the cardinality of the test suite (i.e., the number of test cases). Second, the matrix has to be mapped into constraints, representing a time complexity of $O(N)$. Third, MINION is executed to compute the solutions for the problem at hand $O(MINION)$. It uses a depth-first search method, in general it will take worst-case exponential time $O(2^N)$, although many problems are in practice solved in polynomial time $O(n^2)$. Fourth,
the results are filtered so that only minimal solutions are kept $O(|D|)$ where $|D|$ is the number of solutions spit by MINION.

All in all, the time complexity of our approach is $O(|T| + N + MINION + |D|)$. It is reasonable to assume that $|T|$ and $|D|$ are of the same order of magnitude as $N$. Thus, time complexity is $O(3N + MINION)$. As the number of tests is smaller than the time complexity, the overall time complexity of our approach is $O(MINION)$.

Theoretically, $O(MINION)$ is a worst-case exponential time $O(2^N)$, but in practice that complexity does not affect the global performance (see Section 5.1.3).

**Space Complexity**

With respect to space complexity, for each invocation of our approach, the complexity is $O(M \times N)$ to keep the coverage matrix and, if $D$ is the number of solutions, $O(|D|)$ to retain all solutions. Therefore, the total space complexity is $O((M \times N) + |D|)$.

**3.6 Summary**

Present Chapter has introduced a new approach to test suite minimization, selection and prioritization using MSC problem. It is based in a coverage matrix that is used to mapping the relation of components with test cases as a set of constraints. This approach can minimize and select tests, creating minimum sets which coverage the same percentage of components, that original set. After minimization, several metrics of prioritization can be applied, e.g., order minimum sets through cardinality.
Test Suite Minimization, Selection, and Prioritization
Chapter 4

Toolset

The first goal of this project was to develop an ecosystem where developers can re-test and debug their software, with new latest studies in the field of regression testing and debugging software. So, we create and integrate Regression-Zoltar (RZOLTAR) in GZOLTAR Project. And, such as GZOLTAR, RZOLTAR should be used in Eclipse IDE to management the test cases.

RZOLTAR should provide several approaches for techniques of regression testing: minimization, selection, prioritization; which can reduce the effort time of re-test the software. Users should be able to choose from a list of possible sets, the preferential minimal set that coverage all project under analysis with the same coverage of original set (with all test cases).

4.1 Process Components

RZOLTAR components can be divided into five main areas (see Figure 4.1):

- Initial Eclipse Integration;
- JUnit and JaCoCo;
- MINION;
- TRIE;
- Visualization and Final Eclipse Integration.

Initial, Eclipse Integration, allows the detection of all open projects, classes and test classes. JUnit and JaCoCo, executes test cases and produce code coverage information, to create the coverage matrix. MINION, read coverage matrix and try to resolve the CSP. TRIE, can filter the results provided by MINION, to eliminate redundant results. At the end, Visualization and Final Eclipse Integration, display the several minimal sets, and integrates into default Eclipse code editors. For a detailed diagram about process components, see Figure 4.2.
4.1.1 Initial Eclipse Integration

Eclipse is a well known open source project of The Eclipse Foundation [Fou11]. Eclipse most known application is its IDE. This tool is used by many programmers around the world, and is supported by many major software companies [Gee05]. It allows software development in many programming languages, even though its native programming language is Java.

On Eclipse, it is possible to automatically detect all open projects in Eclipse IDE, so GZOLTAR plug-in can then work with them. After having a list of the open projects, GZOLTAR search them for all its packages, java files, classes and methods; thus classes that have JUnit syntax has marked such as ‘Test’ class to be execute later. To avoid differences between the source files and the compiled classes, at this stage it is built the entire project, to guarantee that GZOLTAR has the latest version of the code. This is essential to the correct work of code coverage, as explained further in more detail. After having all information about all open projects, and knowing which one are test classes, GZOLTAR plug-in is ready to start the next stage.

4.1.2 JUnit & JaCoCo

For each project there is a list of all test classes. For each test class all the code is instrumented, to allow the code coverage process. That process aims to detect if a given line of code was or not executed, during an execution. All open projects are instrumented, because open projects can call methods from other projects. After that, test classes are executed. Test classes are Java classes that implement JUnit syntax.
Returned value will be stored at test class respectively, to be used later by the RZOLTAR View, to show if test passed, failed or happened an error. Then code coverage results are analyzed. Test classes are ignored during code coverage analysis, because they are not important to calculate the regression set. At this stage is possible to store the Coverage Matrix line about this test (see Section 3.1). Because the project was automatically built at the time of project and class detection, it is guaranteed that the code coverage made against compiled classes corresponds exactly to the source code files. This is essential to avoid errors in code analysis. If this procedure was not considered, code coverage information could point to the wrong line of code.

JaCoCo [Hof11a], a recent project from the EclEmma [Hof11b] project team was used. JaCoCo can instrument Java code, execute it and analyze each line of code to check if it was executed or not. EclEmma is based on Emma [Rou11], a discontinued project. Because of that, EclEmma project team started a brand new project to create Java Code Coverage. This project is JaCoCo, which started in mid of 2009. JaCoCo was been presented on Eclipse Summit Europe 2010 [Hof11c] and now has totally integrated in EclEmma. Java instrumentation is much more complex than a native application one, because Java code coverage tools have to deal with Java Virtual Machine (VM). JaCoCo is an Application Programming Interface (API) that allow the integration of Java code coverage functionalities on GZOLTAR.

Performing a code coverage analysis with JaCoCo is based on three steps:

- Instrumentation of the code to be analyzed;
- Execution of that code;
- Code coverage data analysis.

RZOLTAR does exactly those three steps. All code from open projects are instrumented, test classes are executed and code coverage data is analyzed. At the end, the Coverage Matrix is built.

### 4.1.3 MINION

After collecting the coverage of SUT, the coverage matrix can be converted into constrains (see Section 3.3) and passed to MINION constraint solver. The MINION project is distributed for the most used operating systems (Microsoft Windows, Mac OS X and also Linux Systems), so the call to MINION is executed in other process with the following parameters:

- No print solutions, `-noprintsols`;
- Sometimes the user choose (in interface) to calculate all solutions, `-findallsols`, sometimes he choose limited solution, `-sollimit`;
- Redirect the solution output to a specific file: `-solsout`.

### 4.1.4 TRIE

The results provided by MINION are filtered by TRIE structure to delete the non minimal sets.
4.1.5 Final Eclipse Integration

While analyzing the several minimal sets, on the RZOLTAR visualization, user can:

1. see the result of test (pass, fail or error) by the color of icon. If test fail or return an error, user can check the message of test result at “Trace” window;

2. double-click on any test case, and jump directly to that test class (an Eclipse code editor is opened, and the text cursor placed on the selected test);

If user correct any failed test, he just need to refresh RZOLTAR (by pressing CTRL + F5, for more details see Section 4.4.) to have an updated version of the system, after the last fault fix. This way, user can perform regression testing tasks (run only minimal sets to test SUT and fix existing faults) at the same place, with the advantage of being a well known tool (Eclipse IDE).

Figure 4.2: RZoltar Detailed Process Flow. All major tasks from RZOLTAR start until show solutions and code editor integration.
4.2 Logical Layers

RZOLTAR uses many different technologies to accomplish its tasks. It is written in Java and is an Eclipse View integrated in GZOLTAR plug-in. To obtain information about open projects, their classes, it uses Eclipse’s Workspace component. RZOLTAR uses JaCoCo, a Java-based API that offers code coverage capabilities and JUnit to execute unit tests. To produce Eclipse User Interface (UI) related tasks, it uses Eclipse’s Workbench component. This component has SWT, that allows the creation of RZOLTAR view. In RZOLTAR, but written in C is the MINION constraint solver. TRIE structure has a interface written in Java and implementation written also in C. For a schematic view of these technological layers, see Figure 4.3.

![Figure 4.3: RZOLTAR Layers. Integration between RZOLTAR and other technologies.](image)

4.3 Modular Architecture

GZOLTAR was developed in a modular way, allowing a faster and organized development in the future. It has seven packages, that work much like service providers between them. In this Section is presented the way GZOLTAR code is encapsulated (for a conceptual representation of GZOLTAR architecture, see Figure 4.4).

4.3.1 Algorithms Package

The main goal of GZOLTAR was to develop a tool that could provide a graphical view of the project under analysis, clearly indicating the fault probability of each module. To do this, the authors of GZOLTAR plug-in implement the algorithm Ochiai. Ochiai, is a statistics-based algorithm for software fault diagnosis. It takes as input component involvement in the execution of a given test case and whether or not the test case has passed. The diagnostic report yielded by Ochiai is a ranked list of components likely to be responsible for observed failures [AZvG07]. So, when “Zoltar” class needs to calculate the software faults, calls “Ochiai” class. New algorithms, for fault localization, developed/implemented in the future should be placed at this package.
4.3.2 CSP Package

The constraint solver used in RZOLTAR plug-in is MINION, so the “Minion” is responsible to interact with that constraint solver: create the input (transform coverage matrix in constraints), call MINION executable and catch the output (result). Similar to “Algorithms Package”, new implementation or calls to others constraint solver should be placed at this package.

4.3.3 Plugin Package

When “GZOLTAR View” or “RZOLTAR View” start, the class “Activator” present in this Package is called. This class has the minimum required code to start-up Eclipse Plug-in. Like “Activator” class, the classes GZOLTAR and RZOLTAR only executes on start-up and only has the minimum required code to start GZOLTAR View or RZOLTAR View.

Two different visualizations were created for “GZOLTAR View”: “Sunburst” and “Treemap”. This visualizations have just a minimal amount of code, because they are focused on data visualization only. They have access to the tree with all needed data, provided by the main “GZOLTAR” class, and to all the needed auxiliary processing is provided by the two classes in the “Utils” package. New visualizations that could be developed in the future should also be placed at this package.

The class “RZOLTAR” prepare the all environment to “RZOLTAR View”, such as copy MINION executable to the temporary folder.

4.3.4 Utils Package

Plug-in also has a special package, called “Utils”, that has many useful services that can be used by the all classes. It has two classes: a “FileUtils”, that provides services related with functions of read or write and delete files, and a “Markers”, that provides services more oriented to generate markers (warnings) into Eclipse code editor. These classes work much like service providers, that offers services to the two main classes, “GZOLTAR” or “RZOLTAR” class, and to all other classes.

4.3.5 Views Package

The two views of GZOLTAR plug-in are: “GZOLTAR View” and “RZOLTAR View”. These views interact directly with user, “GZOLTAR View” use Open Graphics Library (OpenGL) technology embedded in an Eclipse View to create all the 3D scenes of the different visualizations, “RZOLTAR View” create a simple Eclipse View with regression sets and a few buttons which can be used to initiate the plug-in, parametrize some options, etc (for more details see Section 4.4.).

4.3.6 Workspace Package

To the save the coverage of all open projects in workspace, GZOLTAR plug-in saves important information of workspace, information such as: name of all open projects, paths to the sources directories and output directory, the name of all packages, sources files, classes, etc. With this
information “Zoltar” class can know how many unit tests that has to execute, register the coverage in respectively line. “RZOLTAR View” also can use this information to integrate view with Eclipse code editor.

### 4.3.7 Zoltar Package

During the utilization of GZOLTAR View or RZOLTAR View, when the user presses **CTRL + F5** key (for more details see Section 4.4.), the class “Zoltar” is invoked from this package. This class has the code to process all automatic debugging results, to be used by the different visualizations. This main “Zoltar” class, that makes all the processing, it also has a second one, “ZoltarTree” that has the model to store the processed tree structured data.

![Diagram of GZOLTAR Modules](image)

**Figure 4.4: GZOLTAR Modules.** GZOLTAR Project is compound by seven packages. “Algorithms” has algorithms to calculate the failure probability of each component. “CSP” has interfaces to classes which trying to resolve the constraint satisfaction problem. “Plugin” has main Eclipse bundle, “GZOLTAR”, “RZOLTAR” class, and the main class “Activator”. “Utils” has several auxiliary classes. “Views” has “RZOLTAR” and “GZOLTAR” tab views. “Workspace” has information about *workspace* from Eclipse, and “Zoltar” has automatic debugging classes.
4.4 Eclipse View

RZOLTAR is compatible with Microsoft Windows, Mac OS X and also Linux Systems (see Fig. 4.5). It is also compatible with 32 and 64 bit Central Processing Unit (CPU) architectures.

By default, RZOLTAR presents an Eclipse View integrated into the IDE, such as many other views, like “Console” or “Problems” (see Fig. 4.6). It is possible however to expand RZOLTAR view by double-clicking on its view tab (with “Regression-Zoltar” label). This way RZOLTAR viewable area gets bigger, but all the other views gets hidden.

RZOLTAR View is responsible for all actions about regression testing. This view is divided in two layers, on the left user can access to the list of minimum set coverage (including the set with all test cases); on the right user can see “Failure Trace” of faulty tests. At two layers, user can always double-click on a test case and jump to the file with test case, or at failure trace, double-click goes to line (presents in that layer).
At RZOLTAR view there are two implicit prioritizations: Cardinality of Set and Runtime. First prioritization can order the minimum sets through the number of tests in every sets. Second prioritization can sort the minimum sets by the total of time which set needed to re-run.

Every time you change your project code, RZOLTAR have to update its information. This is not made automatically because of performance reasons. To do so, click on “Refresh” button (CTRL + F5) or if you already do this, you can only select a set of tests and click on Re-Run, to run again the selected set. You will then see a view with the updated data. If you are working with big projects, it is normal if you have a delay between the time you press “Refresh” button and have the view ready to navigate. User can always clear, expand and collapse results, with respectively buttons (see Figure 4.7).

How many time do you have to wait for best solutions? Clear results Collapse All

Re-Run the selected set Refresh results (CTRL + F5) Expand All

Figure 4.7: RZOLTAR Toolbar.

From the left to the right, in Figure 4.7 appears: ‘Re-Run’, ‘Time/Solutions’, ‘Refresh’, ‘Clear Results’, ‘Expand’ and ‘Collapse’. Re-run allows the re-execution of a selected set. Time/Solutions provides some options to user, related with time to calculate the minimum set coverage, for example, “I want to wait 30sec (max limit) for a minimum solution”, or “I want the first 100 minimum solutions”. Refresh, runs all unit tests presented in Java project, and calculate the minimum set coverage. Clear results, erase the RZOLTAR view. Expand and Collapse, show/hide the sets in RZOLTAR view.

4.5 Summary

This chapter presented the system’s implementation of the proposed architecture for RZOLTAR. It can be concluded that integration Regression Testing with GZOLTAR, dubbed RZOLTAR, is working as expected. The interaction with user is very intuitive (more information in next chapter with user studies), because it was used familiar icons and colors from Eclipse themes.
Chapter 5

Evaluation

This chapter presents an evaluation of the results achieved by two evaluations: empirical and with user studies. In order to empirically evaluate the performance and results the approach presented in Chapter 3 three open-source programs were used. The goals of this evaluation were to measure the percent reduction in test suite achieved by RZOLTAR, and to measure the analysis time to achieve the test set reduction. To evaluate the usability of GZOLTAR, an open-source program was used. The study give to users some minutes to find a fault previously injected in source-code.

5.1 Empirical Evaluation

To assess the performance of our approach, we performed an empirical evaluation using several software subjects. In our evaluation, we investigate the following research question:

RQ1: Can RZOLTAR find an optimal solution for a test suite minimization problem in a reasonable time?

Sections 5.1.1 and 5.1.2 presents the software subjects that we used in the study and our experimental setup. Section 5.1.3 illustrates and discusses our experimental results.

<table>
<thead>
<tr>
<th>Subject</th>
<th>Description</th>
<th>Version</th>
<th>Classes</th>
<th>Unit Tests</th>
<th>LOCs</th>
<th>Coverage</th>
</tr>
</thead>
<tbody>
<tr>
<td>NanoXML</td>
<td>XML parser</td>
<td>2.2.3</td>
<td>32</td>
<td>9</td>
<td>5483</td>
<td>52%</td>
</tr>
<tr>
<td>org.jacoco.report</td>
<td>Report generation</td>
<td>0.5.5</td>
<td>93</td>
<td>225</td>
<td>5973</td>
<td>97.2%</td>
</tr>
<tr>
<td>JTopas</td>
<td>Text data parser</td>
<td>0.8</td>
<td>64</td>
<td>57</td>
<td>9037</td>
<td>84.3%</td>
</tr>
</tbody>
</table>

Table 5.1: Subject program used in the empirical study
5.1.1 Experimental Subjects

Three subjects written in Java are used in the empirical study. NanoXML is a small XML parser for Java [Sch12]. org.jacoco.report is a module of JaCoCo project that has utilities for report generation [Hof11a]. JTopas is a Java library used for parsing text data [Bla12]. Table 5.1 provides summary information about the subjects programs. The first object have Test Specification Language (TSL) suite [OB88], all tests are defined by a input/output file which contains the input for every test and respectively output expected. The last two have JUnit test suites. For each program, the table shows a description, the official version that we considered, the number of classes, the number of JUnit test classes, the number of JUnit test methods, the number of lines of code (non-comment lines), and the percentage of coverage. To gather that coverage data, we used an Eclipse plug-in, Metrics\(^1\), to perform coverage analysis.

5.1.2 Experimental Setup

All subjects, except NanoXML have unit tests written in JUnit. For NanoXML, we have create several test cases in JUnit with the inputs from test files (defined in NanoXML project) and insert an assert to check if the output of the test case is equal to the output from output file, as expected. With this we still maintaining the same purpose and inputs/outputs of tests.

For NanoXML, we have create a several test cases, which is the mapping of TSL tests into JUnit tests. We create a test with the inputs from test files (defined in NanoXML project) and insert an assert to check if the output of the test case is equal to the output from output file, as expected. So, we can ensure the same purpose of test in TSL and JUnit. To org.jacoco.report and JTopas, we convert all JUnit test cases, in real unit tests. These two subjects have a lot of test case which have at least two or three unit tests. So, to check the real purpose of every unit test, we transfer every unit test presenting in test case to a single test case (e.g. if a test case has 3 unit test (u1, u2 and u3), we create test case c1 with u1, c2 with u2, and c3 with u3, with all needed definitions). This transformation is valid and legitimate, because does not change source code, or increase/decrease percentage of coverage or number of tests. It has necessary to do that because RZOLTAR, has a technological limitation. It does not handle the individual tests in a suite per set, but considers each suite as one test.

For three subjects ten experiences are made. For each one we measured how long RZOLTAR took to compute a solution and the cardinality of solutions (minimum sets) founded. We also calculate the average and the standard deviation taken by our approach (refer to table Table 5.5 for further information).

For our experiments, we ran all subjects on Linux, on a 2.27 Ghz Intel Core i3-350M with 4 GB of RAM running Debian Gnu/Linux Wheezy.

5.1.3 Results and Discussion

Experimentation shows that for large programs a significant reduction in the test suite may be achieved. The reduction for our examples ranged from 11% to 75%, in 0.1 seconds and 2 seconds, respectively.

RQ1 Can RZOLTAR find an optimal solution for a test suite minimization problem in a reasonable time?

To answer RQ1, we first analyzed the data collected in our experiments (see Appendix C for more details).

By looking at the data in Table 5.2 we found that RZOLTAR can compute, at least, a solution for all of the cases considered. The reduction for subjects ranged from 11.11% in case of NanoXML, to a significant result of 75.56% in org.jacoco.report subject.

<table>
<thead>
<tr>
<th>Subject</th>
<th>#Original Suite</th>
<th>#Minimized Suite</th>
<th>% of reduction</th>
</tr>
</thead>
<tbody>
<tr>
<td>NanoXML</td>
<td>9</td>
<td>8</td>
<td>11.11%</td>
</tr>
<tr>
<td>org.jacoco.report</td>
<td>225</td>
<td>55</td>
<td>75.56%</td>
</tr>
<tr>
<td>JTopas</td>
<td>57</td>
<td>26</td>
<td>54.39%</td>
</tr>
</tbody>
</table>

Table 5.2: Percentage of size reduction. The #Minimized Suite represent the smallest set found.

In NanoXML and JTopas subjects, RZOLTAR was able to return more than one minimum set coverage. For NanoXML it returns 2 sets, each set with 8 tests. As we can see in Table 5.3, for JTopas, RZOLTAR returns several minimum sets (all with the same number of tests, 26), dependently the parameter defined in ‘Time/Solutions’ button (see Section 4.4).

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Number of Minimum Sets</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 second</td>
<td>6</td>
</tr>
<tr>
<td>30 seconds</td>
<td>12</td>
</tr>
<tr>
<td>60 seconds</td>
<td>12</td>
</tr>
<tr>
<td>first 100 solutions</td>
<td>2</td>
</tr>
<tr>
<td>first 1000 solutions</td>
<td>4</td>
</tr>
</tbody>
</table>

Table 5.3: Number of minimum sets for JTopas subject

Next, we measure how long it took for RZOLTAR to compute one solution, Table 5.4 shows the results of this analysis.
The results in Table 5.4 show that RZOLTAR was able to find an optimal solution for all subjects in 1 second, and in most cases the solution was computed in less than 0.5 seconds. And like we said in Chapter 3, MINION is a really fast constraint solver, e.g., in JTopas subject, with 9037 constraints (number of Lines of Code (LOC)s) and 57 variables, MINION can return six minimum sets in 1.198 seconds. The Trie usage time is also rather satisfactory. In NanoXML and org.jacoco.report the time spent in the Trie is marginal. In JTopas the time spent there is about 1 second.

Overall, when reducing the size of the original test suite, one reduces the time needed to achieve the same coverage. Table 5.5 presents the time needed to execute the original set, as well as the reduced set (minimum set) proposed by RZOLTAR.

<table>
<thead>
<tr>
<th>Subject</th>
<th>(Original Set)</th>
<th>σ</th>
<th>(Minimum Set)</th>
<th>σ</th>
<th>% of reduction</th>
</tr>
</thead>
<tbody>
<tr>
<td>NanoXML</td>
<td>1.976</td>
<td>0.064</td>
<td>1.723</td>
<td>0.077</td>
<td>12.81%</td>
</tr>
<tr>
<td>org.jacoco.report</td>
<td>39.004</td>
<td>0.484</td>
<td>10.671</td>
<td>0.197</td>
<td>72.64%</td>
</tr>
<tr>
<td>JTopas</td>
<td>275.673</td>
<td>0.586</td>
<td>157.717</td>
<td>0.480</td>
<td>42.80%</td>
</tr>
</tbody>
</table>

Table 5.5: Time (in seconds) reduction from original set to minimum set

Similar to the results reported for the cardinality, the time reduction for minimum sets have the same range of values, e.g., for org.jacoco.report the percentage of time reduction is about 70%, like percentage of size reduction.

5.2 User Study

In order to validate the usefulness of the current version of the plug-in, nine users were selected to test the efficiency of the interactive visualizations. It was recorded the time that each user took to finish the testing and debugging task. At the end of this process, each user filled a form (see Appendix D) with the feedback of their experience and some suggestions for future work. This usability test was important not only to test the efficiency of the presented plug-in but also to aid the development team to fulfill the user’s needs in future versions of this tool.
5.2.1 Users Description

Nine developers composed the users group. The users were picked randomly from the Department of Informatics Engineering of the Faculty of Engineering at the University of Porto, Department of Informatics of the Faculty of Science at the University of Lisbon and Universidad Complutense of Madrid, Spain. The number of users was based on J. Nielsen’s work related with usability and user tests [NL93]. Nielsen advocates that for a small software project, nine is in the optimal range of users to participate in the usability test [NL93]. This small number of users should be enough to identify the main usability issues. This experiment was conducted to identify the main users' difficulties while using the GZOLTAR plug-in (RZOLTAR View and GZOLTAR View). This information was helpful to create guidelines to improve future developments of this tool, and to have a first assessment of the impact of this plug-in among the users.

The user group was composed by MSc and PhD students and professors in Informatics Engineering, aged 22 to 27 years old, and from both genders. The users were familiarized with three main operating systems: Linux (89%), Microsoft Windows (78%) and Apple Mac OS X (33%). The most common programming languages used by the group members were Java (100%), C (100%), C++ (89%), and PHP (89%), C# (67%), Python (67%) and Assembly (56%). The majority of the developers used regularly an IDE, being the most popular IDEs Eclipse (89%), NetBeans (22%) and Microsoft Visual Studio (67%). There was however one user who did not use regularly any IDE (uses VIM to develop). The most used debugging techniques were breakpoints (89%) and “print” statements in the code (78%). JUnit is the main testing tool used by the group (78%). On the other hand, two elements of the group stated that they do not use any particular testing technique.

5.2.2 Experiment Conditions

Computers with Linux and the Eclipse IDE with the GZOLTAR plug-in were used for this user study. Each user was asked to debug a faulty version of the NanoXML v2.2.3 application [Sch12]. This is an open source, medium size application with 5483 lines of code and a suite of JUnit tests. A fault was injected in the class `XMLUtil`, which can be found in the `net.n3.nanoxml` package. Line 109 (method `skipTag`) was modified from `case '>':` to `case ']':`, making some test cases fail. Users had no previous contact with the application source code and the JUnit tests. A brief explanation (about 5 minutes) was given to each user to explain the assignment and the workflow of GZOLTAR. The users were given 20 minutes to test and localize the fault. After the debugging task, each user filled a survey with questions on their experience.

5.2.3 Results and Feedback

As mentioned before, the time limit for this task was very short - only 20 minutes. The goal was not to record how long the users would take to find and fix the faults, but to obtain feedback about the plug-in usability and usefulness by a set of independent users. It is important to note that
Evaluation

71.4% of the users were able to find the fault in less than 20 minutes (and 42.9% even fixed the fault to ascertain that the suspicion was justified). It is important to highlight that the users did not know which application was going to be used in the experiment, and they did not have any previous knowledge about the source code. From the users that were not able to find and correct the fault, 50% were able to point the most likely fault localization. However, because they were not able to fix the fault, they could not confirm that the fault localization was right. It is important to note that some users were rather uncomfortable with the Eclipse IDE because they never used it or they did not use it on a regular basis.

The survey had a section where the users answered questions related with their profile and development experience, and a section where the users could give their feedback. Replies to the questions about the plug-in interface, performance and embedded concepts were made using a scale from 1 (unacceptable) to 5 (excellent).

A considerable amount of users (44%) found the plug-in difficult to understand at the first. However, the majority (56%) stated that they understood how the tool works in a short period of time. The debugging tasks, using GZOLTAR plug-in, were considered fast and logic by 78% of the users.

The users group also analyzed the performance of the plug-in. An expressive slice of the group (77%) considered the responsiveness of the plug-in as very good. The same number of users (77%) found that the plug-in usefulness increased with their experience and knowledge about the tool. Most importantly, all the users considered that they were able to obtain good results with little knowledge about the tool operation.

The users group also gave feedback about the concepts embedded in GZOLTAR. All the users considered automatic debugging as an important concept, where 67% classified it as “essential”. Debugging techniques integrated into IDE were also considered important, having the majority of users (56%) considering them as “essential”. A large number of users (78%) also considered visual debugging as an important concept.

Also, users report the global experience using RZOLTAR and GZOLTAR View. To RZOLTAR View, users (66%) classified it as easy to use. For GZOLTAR View, they consider (44%) their experience median.

The final part of the survey had an open question where the users could leave their comments and suggestions. Some suggestions were related with the colors. Some users found that the full-color spectrum affected negatively the visualization analysis. They suggested the limitation of the number of colors (having for example color red for “high probability”, yellow for “low probability” and green to “no probability”). The users’ comments were very positive. Two users stated that without the GZOLTAR plug-in, they would probably never find the software faults, because
Evaluation

they did not know the software they were testing.

This experiment with developers validated our hypothesis. An interactive visualization of automatic debugging reports can help developers to find the faults localizations in a short period of time. Moreover, an IDE plug-in facilitates not only the faults localization but also the fixing of the localized faults. Even not knowing the faulty software, most of the participants were able to find and fix the faults in less than 20 minutes.

5.3 Summary

In summary, RZOLTAR provides a practical and efficient approach to determine the minimum set coverage for any program with JUnit tests.

The performance of our approach was evaluated with several experiences, using three open-source programs: NanoXML, org.jacoco.report and JTopas. Empirical evaluation show that approach can handle large program without sacrifice performance, e.g. for JTopas with 9037 constraints and 57 variables, minimum set coverage can be determined in 2 seconds. In general the results were much satisfactory and in some case the percentage of reduction the original set, was about 75% and save 43% of time to re-execute the minimum set.

Relative to the interface and interaction of user with GZOLTAR, the effectiveness of tool was assessed with an usability test, performed with a small group of informatics engineering MSc and PhD students. The results of this study were very positive, and shown that users found GZOLTAR to be a powerful testing and debugging tool. The study was also useful to get users feedback to aid in future developments of this tool.
Evaluation
Chapter 6

Conclusions and Future Work

In this manuscript, we started by looking at the current issues of the software testing field, specifically about regression testing: (1) time costs associated to re-test a software when some new features are developed or some old features are removed, and (2) tools to support testers to make the regression testing a simple and quickly task. Behind this status we provide a study about several techniques for regression testing: minimization, selection and prioritization. To prove the veracity of our approach a tool was developed to make the regression testing task as more easiest as possible.

6.1 Work Summary

Our first contribution was in the field of test suite minimization. The problem in identifying what tests will be chosen to be re-run was mapped to a CSP and solved using the state-of-the-art solver MINION [GJM06]. After identifying the minimal subsets of tests to run, we can select any set, because we have confidence that all requirements have been satisfied. In terms of prioritization, the subsets may be prioritized (ordered) through two metrics: cardinality of the set and runtime.

Finally, we created an ecosystem in GZOLTAR, where developers can use features such as Debugging & Testing in the same tool.

6.2 Future Work

The initial goals were all achieved, even much more new goals that came during RZOLTAR development were achieved. There are always new ideas, on an almost daily basis, that could improve RZOLTAR project. Even during the case studies, when RZOLTAR plug-in was considered ready, there were new good ideas to improve RZOLTAR behavior.
Conclusions and Future Work

6.2.1 Convert Test Suite into Test Case

RZOLTAR try to find the minimum set coverage in some Java project, but if exist a Test Suite which invoke all Test Cases presented in project, RZOLTAR select that test suite to be the minimum set coverage. This happen because test suite execute all test case, which covers all program, so test suite cover all program, too, with the same percentage. Converting automatically test suite into several test cases can be interesting to implement in RZOLTAR, because could be more efficient to determine the minimum set coverage.

6.2.2 Improve performance of RZOLTAR

There is an unofficial version of RZOLTAR which use Ant\(^1\) to execute and register the coverage for every unit tests. But that version it is less efficient (in time) then official version. So, in future that should be explored to improve the unofficial version in some way, to a perfect performance.

6.2.3 New Techniques for Prioritization

Prioritization by cardinality or runtime execution of set are two powerful techniques, although new prioritization should be implemented in future, e.g. ranking minimum sets by number of faults that can detect, bayesian probabilities, etc.

6.3 Side-Work

During the study/development of this project, I had the opportunity to participate in an summer internship and a competition, which gave me a totally unique experience.

6.3.1 Summer Trainee at Critical Software\(^2\)

For two months I make a summer internship at Critical Software. This experience gave me the opportunity to improve my technical skills, as well personal/interpersonal.

In the technical field, I had contact with technologies which hitherto had not used, e.g., Concurrent Versions System (CVS), Jira - a project tracking tool, Bugzilla, Wise, and a development environment completely unknown for me. The main goal of the project in which I was involved, was to validate the requirements of control system present in SWARM project. SWARM is a trio of satellites for a unique view inside the Earth The Swarm mission will provide the most detailed data yet on the geomagnetic field of the Earth and its temporal evolution, giving new insights into improving our knowledge of the Earth’s interior and climate.

At level personal/interpersonal, the experience allowed to improve my way to interact with complete strangers as well as the integration on teams that was already formed and with several routines.

Conclusions and Future Work

6.3.2 DXC’11

NASA Ames Research Center (ARC), Palo Alto Research Center (PARC), and Delft University of Technology decided to combine efforts to create a generalist framework that would establish a typically platform to evaluate and compare diagnosis algorithms [KNP+09]. The goals for developing this framework are to increase research in theories, principles, and computational techniques for monitoring and diagnosis of complex systems.

The First International Diagnostic Competition happens in 2009 and was the first implementation of the above referred framework [KNP+09]. The Third International Diagnostic Competition (DXC’11)\(^3\) includes the same diagnostic problems (present in other past editions), and use cases for the industrial and synthetic tracks as DXC’10. In 2011 the competition implement a new feature, a software track. The objective of this track is to provide typically evaluation techniques that diagnose failures in software systems. In particular, the programs used in this track were taken from both the Siemens and Software Infrastructure Repository (SIR) benchmark programs.

Therefore, we decided to submit the Ochiai algorithm in this year’s competition (DXC’11). Ochiai, is a statistics-based algorithm for software fault diagnosis. It takes as input component involvement in the execution of a given test case and if the test case passed or not. The diagnostic report produced by Ochiai is a ranked list of components likely to be responsible for observed failures [AZvG07].

The averaged metrics for each of the three Diagnosis Algorithm (DA) (Ochiai, Raptor-H and Raptor-EPS2) that participate on this year’s competition are represented in Table 6.1 [SDH11].

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<th>Metrics</th>
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<td>Ochiai</td>
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<tr>
<td>Raptor-H</td>
<td>26413</td>
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<tr>
<td>Raptor-EPS2</td>
<td>11056</td>
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Table 6.1: Diagnostic problem IV metrics [SDH11]. \(M_{\text{probe}}\) represent the probing cost metric, \(M_{\text{cd}}\) represent the residual diagnostic effort, and \(M_{\text{mem}}\) represent the memory load.

Both Raptor-H and Raptor-EPS2 have much inferior probing costs than Ochiai. Denote that this is an dishonest comparison since Raptor first includes a test selection heuristic, whereas Ochiai just executes every possible test. Additionally, Raptor-H and RaptorEPS2 have lower residual diagnostic effort as well. Per program, Raptor-H performs better in the cases where the precomputed information has a low error. On average, however, there is little difference between both algorithms. Finally, when it comes to memory consumption, Ochiai is the winner since it is a much lighter-weight approach than Raptor-* Bayesian diagnosis.

\(^3\)DXC Competition [https://sites.google.com/site/dxcompetition2011/], 2012.
Appendix A

Meetings Summaries

Description of the subjects raised in the meetings between student and supervisor.

A.1 During Dissertation Planning

A.1.1 28th January, 2011

• Raised Subjects
  – Set the dissertation proposal to submit in the MIEIC.

• Future Work
  – Write the dissertation proposal.

A.1.2 4th February, 2011

• Raised Subjects
  – Set the proposal to submit in the HP Labs Innovation Research Program.

• Future Work
  – Write two/three paragraphs about the subject of dissertation.

A.1.3 9th February, 2011

• Raised Subjects
  – Finishing the proposal to HP.

• Future Work
  – Reread the proposal and report feedback.
Meetings Summaries

A.1.4 16th February, 2011

- Raised Subjects
  - Keyworks.
  - Discuss a diagram that elucidates the way to go in this phase. Tests, test types, regression testing, how testing is approached by developers (what kind of tools are used, methodologies, etc.).
  - Influence authors on subject Test and special in Regression Testing.

- Future Work
  - Experiment, test and evaluate which frameworks, JUnit or TestNG is the most appropriate to this project.

A.1.5 23rd February, 2011

- Raised Subjects
  - Difference between JUnit and TestNG frameworks. Show a practical example.
  - How GZOLTAR use JUnit or TestNG? We will not implement JUnit or TestNG on GZOLTAR, because this would limit upgrade of GZOLTAR. Instead, GZOLTAR ask for services from JUnit or TestNG.
  - How Microsoft Visual Studio 2010 implements unit tests.

- Future Work
  - Performance test of both frameworks.
  - Search for paper with related work on Microsoft Research (MSR).

A.1.6 03rd March, 2011

- Raised Subjects
  - Performance of JUnit vs TestNG.
  - Architecture of GZOLTAR: how as implemented, data structures, where new module will be integrate to communicate with JUnit?
  - Similiar tools about regression testing? MINTS.
  - After the version 4.6 of JUnit, it has a new module called MaxCore (it remember the last execution of tests; prefer new test to old; quick tests to slow tests; tests that have failed for some time rather than the tests that failed a long time).

- Future Work
  - Analysis GZOLTAR architecture.
Meetings Summaries

A.1.7 04\textsuperscript{th} April, 2011

- Raised Subjects
  - Timeline.
  - Minimization Heuristics: Greedy, HSG, Delay-Greedy, Selective Redundancy, Bi-Criteria, ILP with one example.
  - Our contribution, Constraint satisfaction problem (CSP).

- Future Work
  - Pseudo-text for Minimization.
  - Begin the study of Selection.

A.1.8 10\textsuperscript{th} May, 2011

- Raised Subjects
  - Talk about first presentation.

- Future Work
  - Begin the study of Prioritization.

A.1.9 14\textsuperscript{th} June, 2011

- Raised Subjects
  - Deadlines.

- Future Work
  - Finish the definition of Regression Testing.
  - Finish the Technique Minimization.

A.1.10 05\textsuperscript{th} July, 2011

- Raised Subjects
  - Delivered the following artifacts: Introduction, Definition of Regression Testing, Technique for Minimization.

- Future Work
  - Finish the Fault-detection and Technique for Selection.
  - Introduction, Motivation, Objectives.
  - Second Presentation.
Meetings Summaries

A.1.11 11th July, 2011

- Raised Subjects
  - Talk about second presentation.

- Future Work
  - Finish the Fault-detection and Technique for Selection.
  - Introduction, Motivation, Objectives.

A.1.12 13th July, 2011

- Raised Subjects
  - Delivered the following artifacts: Fault-detection, Technique for Selection.

- Future Work
  - Finish the Technique Prioritization.
  - Abstract.

A.1.13 19th July, 2011

- Raised Subjects
  - Delivered the following artifacts: Technique for Prioritization, Abstract, Introduction, Motivation, Objectives.

- Future Work
  - Begin the second phase of the Dissertation.

A.1.14 20th July, 2011

- Raised Subjects
  - Delivered the final version of 'Regression Testing with GZOLTAR: Techniques for Test Suite Minimization, Selection, and Prioritization’.

- Future Work
  - Vacation, and after that, begin the second phase of the Dissertation.
Meetings Summaries

A.2 During Dissertation

A.2.1 23rd September, 2011

• Raised Subjects
  – Meeting with André to share the last version of GZOLTAR.

• Future Work
  – Create the repository to the group (Rui, André, José, Alex, João, Nuno).
  – Integrate in existing source code.

A.2.2 7th October, 2011

• Raised Subjects
  – Create the repository.

• Future Work
  – Integrate in existing source code. (continue)

A.2.3 14th October, 2011

• Raised Subjects
  – Implementation of TRIE structure in Java.
  – Update JaCoCo plug-in to the last stable version.

• Future Work
  – Try to integrate MINION with GZOLTAR.

A.2.4 21st October, 2011

• Raised Subjects
  – Update the structure of GZOLTAR plug-in.
  – Integration of MINION with GZOLTAR.

• Future Work
  – Create the View for Regression-Zoltar.
Meetings Summaries

A.2.5 28th October, 2011

- Raised Subjects
  - First commit of Regression-Zoltar View.

- Future Work
  - Compile GZOLTAR & RZOLTAR to all plataforms.

A.2.6 4th November, 2011

- Raised Subjects
  - Update Regression-Zoltar View.
  - Talk about the limitation of RZOLTAR (projects that has unit test and need external files to run).

- Future Work
  - Try to integrate Ant with RZOLTAR.

A.2.7 11th November, 2011

- Raised Subjects
  - Update JaCoCo plug-in to the last stable version.
  - Change 'String’ to 'StringBuilder’ (thanks Nuno).

- Future Work
  - Try to integrate Ant with RZOLTAR. (continue)

A.2.8 18th November, 2011

- Raised Subjects
  - Update RZOLTAR View. Add button to choose, how much wait for results?

- Future Work
  - Try to integrate Ant with RZOLTAR. (continue)
Meetings Summaries

A.2.9 25th November, 2011

• Raised Subjects
  – Update RZOLTAR View. Disable icons at beginning.
  – Update GZOLTAR & RZOLTAR integration. Create Global Workspace Information to the two views.

• Future Work
  – Try to integrate Ant with RZOLTAR. (continue)

A.2.10 2nd December, 2011

• Raised Subjects
  – Talk about the integration of Ant with RZOLTAR.
  – New version of TRIE to MacOs.

A.2.11 9th December, 2011

• Raised Subjects
  – Update RZOLTAR View. Add the option ’All Tests’.
  – Fix some bugs.

• Future Work
  – Start the manual and prepare one project example to Human Study.

A.2.12 15th and 16th December, 2011

• Raised Subjects
  – Human Study.

• Future Work
  – Try to implement JUnit plug-in methods and JaCoCo calls on RZOLTAR.

A.2.13 30th December, 2011

• Raised Subjects
  – It is not possible to implement the JUnit plug-in and JaCoCo plug-in on RZOLTAR.

• Future Work
  – Re-start writing the thesis report.
Meetings Summaries

A.2.14 4th January, 2012

- Raised Subjects
  - Meeting with supervisor to define the last things to do.
  - First version of IJUP2012 paper.

- Future Work
  - Correct and finish the IJUP2012 paper.

A.2.15 5th January, 2012

- Raised Subjects
  - Submitted the 'RZOLTAR: a plug-in Eclipse for Regression Testing' to IJUP2012.

- Future Work
  - Writing the thesis report. (continue)

A.2.16 16th January, 2012

- Raised Subjects
  - Feedback of chapter 3.

A.2.17 18th January, 2012

- Raised Subjects
  - Feedback of chapter 6.

A.2.18 22nd January, 2012

- Raised Subjects
  - Feedback of chapter 3.

A.2.19 26th January, 2012

- Raised Subjects
  - Feedback of chapter 5.

A.2.20 27th January, 2012

- Raised Subjects
  - Feedback of abstract.
Appendix B

Performance - JUnit vs TestNG

B.1 Calculator Project

In Table B.1 are represented all values that we measured during the performance test between JUnit and TestNG frameworks. For each framework we use several sizes of test suite, 10, 50, 100, 500, 1000 represented by IT and for each test suite we regist 100 measures, represented by IEl. We run all tests suites on Linux, on a 2.27 Ghz Intel Core i3-350M with 4 GB of RAM running Debian Gnu/Linux Wheezy.

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<th>JUnit</th>
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## Performance - JUnit vs TestNG

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<tr>
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</tr>
</tbody>
</table>

### Table B.1: Executions time of different size of test suite with JUnit and TestNG frameworks
### Appendix C

#### Empirical Evaluation, detailed results

Tables C.1, C.2, and C.3 presented the detailed results from empirical evaluation.

### C.1 NanoXML

<table>
<thead>
<tr>
<th>Experiences</th>
<th>Original Suite</th>
<th>Minimal Suite</th>
<th>RZOLTAR</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>**</td>
<td>Suite 1: 8</td>
<td>Suite 2: 8</td>
</tr>
<tr>
<td>1</td>
<td>9</td>
<td>2.082s</td>
<td>1.829s</td>
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<tr>
<td>2</td>
<td>2.008s</td>
<td>1.780s</td>
<td>1.784s</td>
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<tr>
<td>3</td>
<td>1.927s</td>
<td>1.760s</td>
<td>1.682s</td>
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<tr>
<td>4</td>
<td>1.927s</td>
<td>1.716s</td>
<td>1.701s</td>
</tr>
<tr>
<td>5</td>
<td>1.900s</td>
<td>1.726s</td>
<td>1.664s</td>
</tr>
<tr>
<td>6</td>
<td>2.047s</td>
<td>1.857s</td>
<td>1.596s</td>
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<tr>
<td>7</td>
<td>1.901s</td>
<td>1.693s</td>
<td>1.674s</td>
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<td>2.007s</td>
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<td>9</td>
<td>1.945s</td>
<td>1.736s</td>
<td>1.726s</td>
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<tr>
<td>10</td>
<td>2.020s</td>
<td>1.797s</td>
<td>1.752s</td>
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<tr>
<td>⟨E⟩</td>
<td>1.976s</td>
<td>1.768s</td>
<td>1.723s</td>
</tr>
<tr>
<td>σ</td>
<td>0.064</td>
<td>0.052</td>
<td>0.077</td>
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<tr>
<td>⟨E⟩ % Reduction</td>
<td>10.55%</td>
<td>12.81%</td>
<td></td>
</tr>
<tr>
<td></td>
<td>TI</td>
<td>% Reduction</td>
<td>11.11%</td>
</tr>
</tbody>
</table>

Table C.1: NanoXML detailed results
Empirical Evaluation, detailed results

C.2 org.jacoco.report

<table>
<thead>
<tr>
<th>Experiences</th>
<th>Original Suite</th>
<th>Minimal Suite</th>
<th>RZOLTAR</th>
<th>MINION</th>
<th>Trie</th>
<th>MINION + Trie</th>
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<td>39.044s</td>
<td>10.582s</td>
<td>0.439s</td>
<td>0.002s</td>
<td>0.441s</td>
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<td>0.447s</td>
<td>0.001s</td>
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<td>0.001s</td>
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<td>10.792s</td>
<td>0.422s</td>
<td>0.001s</td>
<td>0.423s</td>
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<tr>
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<td>10.882s</td>
<td>0.427s</td>
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<tr>
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<td>0.003s</td>
<td>0.420s</td>
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</tbody>
</table>

| ⟨E⟩         | 39.04s         | 10.671s       | 0.429s  | 0.002s | 0.430s |
| σ           | 0.484          | 0.197         | 0.015   | 0.001  | 0.014  |
| ⟨E⟩ % Reduction | 72.64%       |
| |T| % Reduction   | 75.56%       |

Table C.2: org.jacoco.report detailed results

C.3 JTopas

<table>
<thead>
<tr>
<th>Experiences</th>
<th>Original Suite</th>
<th>Minimal Suite</th>
<th>RZOLTAR</th>
<th>MINION</th>
<th>Trie</th>
<th>MINION + Trie</th>
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<tbody>
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<td>157.444s</td>
<td>157.338s</td>
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<td>157.710s</td>
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<td>158.778s</td>
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<td>276.360s</td>
<td>157.495s</td>
<td>157.232s</td>
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<td>157.637s</td>
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<td>157.606s</td>
<td>157.509s</td>
<td>157.570s</td>
<td>157.700s</td>
<td>157.622s</td>
</tr>
</tbody>
</table>

| ⟨E⟩         | 275.673s       | 157.891s      | 157.771s| 157.830s| 157.896s| 157.889s      | 157.717s | 1.198s | 1.016s | 2.214s |
| σ           | 0.586          | 0.535         | 0.586   | 0.541   | 0.458   | 0.454         | 0.480    | 0.011  | 0.015  | 0.019  |
| ⟨E⟩ % Reduction | 42.73%        | 42.80%        | 42.70%  | 42.70%  | 42.70%  | 42.80%        |
| |T| % Reduction   | 54.39%        |

Table C.3: JTopas detailed results
Appendix D

Survey

Figure D.1: Survey - Introduction.

Figure D.2: Survey - User profile.
Figure D.3: Survey - Experience.
Figure D.4: Survey - Interface of GZOLTAR and RZOLTAR.

Figure D.5: Survey - Capacity of plug-in.
Survey

<table>
<thead>
<tr>
<th>Usabilidade Graphical-Zottar &amp; Regression-Zottar</th>
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<tbody>
<tr>
<td><strong>Conceptos</strong></td>
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<tr>
<td>Q15. Considera que o Debugging Automático tem muito ou pouco importância?</td>
</tr>
<tr>
<td>1 2 3 4 5</td>
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<tr>
<td>Fica muito</td>
</tr>
<tr>
<td>Q16. Considera que o Debugging Integrado com Ambiente de Desenvolvimento (IDE) tem muito ou pouco importância?</td>
</tr>
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<tr>
<td>Fica muito</td>
</tr>
<tr>
<td>Q17. Considera que uma ferramenta de Debugging Visual tem muito ou pouco importância?</td>
</tr>
<tr>
<td>1 2 3 4 5</td>
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<tr>
<td>Fica muito</td>
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</tbody>
</table>

**Figure D.6: Survey - Concepts.**

<table>
<thead>
<tr>
<th>Usabilidade Graphical-Zottar &amp; Regression-Zottar</th>
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<td><strong>Experiência global de utilização</strong></td>
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<tr>
<td>Q20. Considera que a experiência global de utilização do Graphical-Zottar foi fácil ou difícil?</td>
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<td>1 2 3 4 5</td>
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<td>Q21. Considera que a experiência global de utilização do Regression-Zottar foi fácil ou difícil?</td>
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<td>Q22. Comentários e sugestões</td>
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</table>

**Figure D.7: Survey - Global experience.**
References


REFERENCES


REFERENCES


REFERENCES


REFERENCES


REFERENCES
